## Harmonic Description of 2-Dimensional Fields

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## **Fields in Free Space: Scalar Potential**

• 
$$\nabla . \mathbf{B} = 0$$
 (Always true)

- In a region free of any currents or magnetic material,  $\nabla \times \mathbf{B} = 0$ , and  $\mathbf{B}$  may be written as the gradient of a scalar potential,  $\mathbf{B} = \nabla \Phi_m$
- The two equations above may be combined to obtain the Laplace's equation for the scalar potential,  $\Phi_m$ ,

$$\nabla^2 \Phi_m = 0$$

## **2-D Fields in Free Space**

• 
$$\boldsymbol{B} = \nabla \Phi_m$$
 and  $\nabla^2 \Phi_m = 0$ 

Most accelerator magnet apertures have a cylindrical symmetry, with a length much larger than the aperture. In such situations, the field away from the ends can be considered 2-dimensional, and the general solution can be expressed in a relatively simple *harmonic series*.

# **Commonly Used Coordinate System**



Users of magnetic measurements data may use a system oriented differently, often requiring suitable transformations of the measured harmonics.

$$B_{y}(r,\theta) = B_{r}\sin\theta + B_{\theta}\cos\theta$$

# **Solution in Cylindrical Coordinates** For no *z*-dependence (2-D fields),

$$\nabla^2 \Phi_m = \left(\frac{1}{r}\right) \frac{\partial}{\partial r} \left(r \frac{\partial \Phi_m}{\partial r}\right) + \left(\frac{1}{r^2}\right) \left(\frac{\partial^2 \Phi_m}{\partial \theta^2}\right) = 0$$

writing  $\Phi_m(r,\theta) = R(r)\Theta(\theta)$ , and imposing the conditions

 $\Theta(\theta + 2\pi) = \Theta(\theta); \quad R(r) = \text{finite at } r = 0$ 

we can get the solution of the Laplace's equation in terms of a harmonic series.

# **2-D Fields: Harmonic Series**

Components of 2-D fields in cylindrical coordinates:

$$B_r(r,\theta) = \sum_{n=1}^{\infty} C(n) \left(\frac{r}{R_{ref}}\right)^{n-1} \sin[n(\theta - \alpha_n)]$$
$$B_{\theta}(r,\theta) = \sum_{n=1}^{\infty} C(n) \left(\frac{r}{R_{ref}}\right)^{n-1} \cos[n(\theta - \alpha_n)]$$

- $C(n) = Amplitude, \alpha_n = phase angle of the 2n-pole term in the expansion.$
- $R_{ref} = Reference \ radius$ , arbitrary, typically chosen ~ the region of interest. C(n) scales as  $R_{ref}^{n-1}$

# **2-D Fields: Cartesian Components**

• Cartesian components of **B** may be written

as:  

$$B_{x}(r,\theta) = \sum_{n=1}^{\infty} C(n) \left(\frac{r}{R_{ref}}\right)^{n-1} \sin[(n-1)\theta - n\alpha_{n}]$$

$$B_{y}(r,\theta) = \sum_{n=1}^{\infty} C(n) \left(\frac{r}{R_{ref}}\right)^{n-1} \cos[(n-1)\theta - n\alpha_{n}]$$

• A *Complex field*,  $B(z) = B_y + iB_x$ , where z = x + iy, combines the 2 equations above:

$$\boldsymbol{B}(\boldsymbol{z}) = \sum_{n=1}^{\infty} \left[ C(n) \exp(-in\alpha_n) \right] \left( \frac{\boldsymbol{z}}{R_{ref}} \right)^{n-1}$$

**2-D Fields: Normal & Skew Terms**  

$$B(z) = B_{y} + iB_{x} = \sum_{n=1}^{\infty} \left[C(n) \exp(-in\alpha_{n})\right] \left(\frac{z}{R_{ref}}\right)^{n-1}$$
may be  
written as:
$$B(z) = \sum_{n=1}^{\infty} \left[B_{n} + iA_{n}\right] \left(\frac{z}{R_{ref}}\right)^{n-1}$$
Simple power  
series, valid within  
source-free zone.

where: 
$$B_n \equiv C(n)\cos(n\alpha_n) = 2n \text{ - pole NORMAL Term}$$
  
 
$$A_n \equiv -C(n)\sin(n\alpha_n) = 2n \text{ - pole SKEW Term}$$

In the US, the 2*n*-pole terms are denoted by  $B_{n-1}$  and  $A_{n-1}$ .

Sometimes, the skew terms are defined without the negative sign, but the above form is the most common now.

#### **Analytic Functions of a Complex Variable**

Any function of the complex variable, z, given by

$$F(z) = U(x,y) + i V(x,y)$$

is an *Analytic* function of *z*, if

$$\left(\frac{\partial U}{\partial x}\right) = \left(\frac{\partial V}{\partial y}\right) \quad \text{and} \quad \left(\frac{\partial U}{\partial y}\right) = -\left(\frac{\partial V}{\partial x}\right) \begin{bmatrix} \text{Cauchy-Riemann} \\ \text{Conditions.} \end{bmatrix}$$

An analytic function can be expressed as a power series in z. This series is valid within the *circle of convergence*, which extends to the nearest singularity. Analytic function does not depend on  $z^*$ .

# **Analyticity of Complex Field**

$$\left(\frac{\partial U}{\partial x}\right) = \left(\frac{\partial V}{\partial y}\right) \quad \text{and} \quad \left(\frac{\partial U}{\partial y}\right) = -\left(\frac{\partial V}{\partial x}\right) \begin{bmatrix} C \\ C \\ C \end{bmatrix}$$

Cauchy-Riemann Conditions.

Maxwell's equations in source free region:

$$\nabla \cdot \boldsymbol{B} = 0 \Longrightarrow \left(\frac{\partial B_{y}}{\partial y}\right) = -\left(\frac{\partial B_{x}}{\partial x}\right) \left( \nabla \times \boldsymbol{B} \right)_{z} = 0 \Longrightarrow \left(\frac{\partial B_{y}}{\partial x}\right) = \left(\frac{\partial B_{x}}{\partial y}\right)$$

Maxwell's equations = Cauchy-Riemann conditions if we choose:  $U(x,y) = B_y(x,y)$  and  $V(x,y) = B_x(x,y)$ Thus,  $B(z) = B_y(x,y) + i B_x(x,y)$  is an analytic function of z. The analyticity is useful in dealing with 2-D problems in magnetostatics.

## **End Fields & Short Magnets**

- The field near the ends of a long magnet, or everywhere in a short magnet, has all three components. The simple 2-D expansion is not valid in these cases. However, if one considers only integrated values of field components, a similar 2-D expansion can be shown to be valid.
- For components of field at a point, a more complex expansion must be used.



## **3-D Field Expansion**

If the field harmonics vary along the axial direction, Z:

$$B_{r}(r,\theta,z) = \sum_{n=1}^{\infty} \left[ B_{n}(z) + \sum_{l=1}^{\infty} \frac{(-1)^{l}(n-1)!(2l+n)}{2^{2l}l!(l+n)!} B_{n}^{[2l]} r^{2l} \right] \left( \frac{r}{R_{ref}} \right)^{n-1} \sin(n\theta) + \sum_{n=1}^{\infty} \left[ A_{n}(z) + \sum_{l=1}^{\infty} \frac{(-1)^{l}(n-1)!(2l+n)}{2^{2l}l!(l+n)!} A_{n}^{[2l]} r^{2l} \right] \left( \frac{r}{R_{ref}} \right)^{n-1} \cos(n\theta)$$

$$B_{\theta}(r,\theta,z) = \sum_{n=1}^{\infty} \left[ B_n(z) + \sum_{l=1}^{\infty} \frac{(-1)^l n!}{2^{2l} l! (l+n)!} B_n^{[2l]} r^{2l} \right] \left[ \frac{r}{R_{ref}} \right] \cos(n\theta)$$
$$- \sum_{n=1}^{\infty} \left[ A_n(z) + \sum_{l=1}^{\infty} \frac{(-1)^l n!}{2^{2l} l! (l+n)!} A_n^{[2l]} r^{2l} \right] \left( \frac{r}{R_{ref}} \right)^{n-1} \sin(n\theta)$$

where the index [2l] denotes  $(2l)^{th}$  derivative with respect to z. If integral values are considered between  $Z_1$  and  $Z_2$  such that all derivatives are zero at the ends, then the above expression reduces to the 2-D expansion.

### **Interpretation of Harmonics**

$$B_{n+1}(\text{European}) = B_n(\text{US}) = \frac{R_{ref}^n}{n!} \left(\frac{\partial^n B_y}{\partial x^n}\right)\Big|_{x=0;y=0}$$

$$A_{n+1}(\text{European}) = A_n(\text{US}) = \frac{R_{ref}^n}{n!} \left(\frac{\partial^n B_x}{\partial x^n}\right) \Big|_{x=0;y=0} \qquad n \ge 0$$

 $B_y = \text{Constant} \Rightarrow \text{Dipole Only}$  $(dB_y/dx) = \text{Constant} \Rightarrow \text{Dipole plus Quadrupole}$ and so on ...

## **Examples of Harmonics**



# Normalized Coefficients: Multipoles

- The coefficients  $B_n$  and  $A_n$  denote the absolute strength of the *n*-th harmonic, and are thus a function of the magnet excitation.
- The variation in the *shape* of the field as a function of excitation is best described using coefficients normalized by a suitable *reference field*, often chosen to be the amplitude of the most dominant term in the harmonic expansion. The normalized coefficients are also referred to as *multipoles*.

## Normalized Coefficients: Multipoles

$$B_{y} + iB_{x} = \sum_{n=n_{0}}^{\infty} \left[B_{n} + iA_{n}\right] \left(\frac{x+iy}{R_{ref}}\right)^{n-n_{0}}; \quad \begin{bmatrix}n_{0} = 0 : \text{US}\\n_{0} = 1 : \text{European}\\n_{0} = 1 : \text{European}\end{bmatrix}$$

$$=B_{ref}\sum_{n=n_0}^{\infty} [b_n + ia_n] \left(\frac{x+iy}{R_{ref}}\right)^{n-n_0}; \text{ where }$$

$$b_n = B_n / B_{ref};$$
  $a_n = A_n / B_{ref}$ 

For a 2m-pole magnet,  $B_{ref}$  chosen as  $|B_m + iA_m|$ 

 $(b_n, a_n)$  independent of current: LINEAR SYSTEM

(b<sub>n</sub>,a<sub>n</sub>)x10<sup>4</sup> = Normal & Skew Multipoles in "UNITS"

# **Properties of Harmonics**

- The Normal and Skew harmonics represent coefficients of expansion in a power series for the field components.
- The harmonics allow computation of field everywhere in the aperture (within a circle of convergence) using only a few numbers.
- These coefficients obviously depend on the choice of origin and orientation of the coordinate system. Measured harmonics, therefore, often need to be *centered* and *rotated*.

### Field in a Non-circular Aperture

The 2-D field expansion in a harmonic series is valid only within the circle of convergence, which extends from the origin to the nearest current element or a magnetic material ("singularity").

For non-circular apertures, a <u>single</u> series expansion may not cover the entire "source-free region", even though the complex field  $B_y + iB_x$  is an analytic function of (x + iy) throughout the aperture. One can circumvent the problem by defining several series expansions, each centered at a different origin.



By having a significant overlap between the various circles of convergence, one can verify the integrity and accuracy of data by comparing results in the overlap regions.

#### **Calculation of Field Outside Convergence Radius**

• The field at any point (x, y) can be computed from the normal and skew harmonics measured at  $(x_0, y_0)$  using:

$$B_{y}(x,y) + iB_{x}(x,y) = \sum_{n=0}^{\infty} (B_{n} + iA_{n}) \left(\frac{(x-x_{0}) + i(y-y_{0})}{R_{ref}}\right)^{n}$$

- For accurate calculations of field, the origin (x<sub>0</sub>, y<sub>0</sub>) should be chosen such that the field point (x, y) is as close as possible, and is well within the circle of convergence defined by the pole tips.
- In special situations, such as when the higher order terms are identically zero, convergence of the series may not be a problem, and it *may* be possible to calculate the field outside the radius of convergence using the same  $(B_n, A_n)$ .



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## **The Vector Potential**

Scalar potential approach does not provide a relationship between the currents and the field.

From Maxwell's equations:

 $\nabla \cdot \mathbf{B} = 0; \quad \therefore \mathbf{B} = \nabla \times \mathbf{A}$  A is called the Vector Potential

$$\nabla \times \mathbf{B} = \mu_0 (\nabla \times \mathbf{H}) = \mu_0 \mathbf{J}$$
 In "free space",  $\mathbf{B} = \mu_0 \mathbf{H}$ 

$$\nabla \times \mathbf{B} = \nabla \times (\nabla \times \mathbf{A}) = \mu_0 (\nabla \times \mathbf{H}) = \mu_0 \mathbf{J}$$

$$\nabla^{2} \mathbf{A} = -\mu_{0} \mathbf{J}$$
**Poisson's Equation**

$$\mathbf{A}(\mathbf{r}) = \left(\frac{\mu_{0}}{4\pi}\right) \int \frac{\mathbf{J}(\mathbf{r'})}{|\mathbf{r} - \mathbf{r'}|} d\mathbf{r'}$$

# Summary

- The 2-D field , away from the ends, in the aperture of a typical accelerator magnet, can be described by a simple power series, valid within a circle extending to the nearest current source or magnetic material.
- A similar 2-D expansion is also valid for 3-D fields if one considers only integrated values of the field components such that there is no axial variation at the boundaries of the integration interval.

# Summary (Contd.)

- The expansion coefficients may be interpreted as spatial derivatives of the field components.
- The expansion coefficients, or harmonics, depend on the choice of coordinate frame. This demands a careful description of the frame when quoting results of measurements. Similarly, users of the data also need to pay close attention to the coordinate definition.

# Summary (Contd.)

- The complex field,  $B(z) = B_y + iB_x$ , is an analytic function of the complex variable, *z*.
- For non-circular apertures, one can describe the field in the entire aperture by defining several series expansions centered at different points in the aperture (*analytic continuation*).
- Scalar potential approach is unsuitable for establishing a relationship between the current and the field. A vector potential approach is more general.