# Harmonic Description of 2-Dimensional Fields 

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## Fields in Free Space: Scalar Potential

- $\nabla . \mathbf{B}=0$ (Always true)
- In a region free of any currents or magnetic material, $\nabla \times \mathbf{B}=0$, and $\mathbf{B}$ may be written as the gradient of a scalar potential, $\mathbf{B}=\nabla \Phi$ $m$
- The two equations above may be combined to obtain the Laplace's equation for the scalar potential, $\Phi_{m}$,

$$
\nabla^{2} \Phi_{m}=0
$$

## 2-D Fields in Free Space

- $\boldsymbol{B = \nabla \Phi _ { m }}$ and $\nabla^{2} \Phi_{m}=0$
- Most accelerator magnet apertures have a cylindrical symmetry, with a length much larger than the aperture. In such situations, the field away from the ends can be considered 2-dimensional, and the general solution can be expressed in a relatively simple harmonic series.


## Commonly Used Coordinate System

## Y-Axis (TOP)



> Users of magnetic measurements data may use a system oriented differently, often requiring suitable transformations of the measured harmonics.

View from the Lead End of the Magnet

$$
B_{x}(r, \theta)=B_{r} \cos \theta-B_{\theta} \sin \theta
$$

$$
B_{y}(r, \theta)=B_{r} \sin \theta+B_{\theta} \cos \theta
$$

## Solution in Cylindrical Coordinates

 For no $z$-dependence ( $2-\mathrm{D}$ fields),$$
\nabla^{2} \Phi_{m}=\left(\frac{1}{r}\right) \frac{\partial}{\partial r}\left(r \frac{\partial \Phi_{m}}{\partial r}\right)+\left(\frac{1}{r^{2}}\right)\left(\frac{\partial^{2} \Phi_{m}}{\partial \theta^{2}}\right)=0
$$

writing $\Phi_{m}(r, \theta)=R(r) \Theta(\theta)$, and imposing the conditions

$$
\Theta(\theta+2 \pi)=\Theta(\theta) ; \quad R(r)=\text { finite at } r=0
$$

we can get the solution of the Laplace's equation in terms of a harmonic series.

## 2-D Fields: Harmonic Series

- Components of 2-D fields in cylindrical coordinates:

$$
\begin{aligned}
& \text { Inates: } \\
& \begin{array}{l}
B_{r}(r, \theta)=\sum_{n=1}^{\infty} C(n)\left(\frac{r}{R_{r e f}}\right)^{n-1} \sin \left[n\left(\theta-\alpha_{n}\right)\right] \\
B_{\theta}(r, \theta)=\sum_{n=1}^{\infty} C(n)\left(\frac{r}{R_{r e f}}\right)^{n-1} \cos \left[n\left(\theta-\alpha_{n}\right)\right]
\end{array}
\end{aligned}
$$

- $C(n)=$ Amplitude, $\alpha_{n}=$ phase angle of the 2n-pole term in the expansion.
- $R_{\text {ref }}=$ Reference radius, arbitrary, typically chosen $\sim$ the region of interest. $C(n)$ scales as $R_{r e f}^{n-1}$


## 2-D Fields: Cartesian Components

- Cartesian components of $\mathbf{B}$ may be written as:

$$
\begin{aligned}
& B_{x}(r, \theta)=\sum_{n=1}^{\infty} C(n)\left(\frac{r}{R_{\text {ref }}}\right)^{n-1} \sin \left[(n-1) \theta-n \alpha_{n}\right] \\
& B_{y}(r, \theta)=\sum_{n=1}^{\infty} C(n)\left(\frac{r}{R_{\text {ref }}}\right)^{n-1} \cos \left[(n-1) \theta-n \alpha_{n}\right]
\end{aligned}
$$

- A Complex field, $\boldsymbol{B}(z)=B_{y}+i B_{x}$, where $z=x+i y$, combines the 2 equations above:

$$
\boldsymbol{B}(z)=\sum_{n=1}^{\infty}\left[C(n) \exp \left(-i n \alpha_{n}\right)\right]\left(\frac{z}{R_{\text {ref }}}\right)^{n-1}
$$

## 2-D Fields: Normal \& Skew Terms

$$
\boldsymbol{B}(z)=B_{y}+i B_{x}=\sum_{n=1}^{\infty}\left[C(n) \exp \left(-i n \alpha_{n}\right)\right]\left(\frac{z}{R_{r e f}}\right)^{n-1}
$$

may be
written as:

$$
\boldsymbol{B}(\boldsymbol{z})=\sum_{n=1}^{\infty}\left[B_{n}+i A_{n}\right]\left(\frac{\boldsymbol{z}}{R_{\text {ref }}}\right)^{n-1}
$$

Simple power series, valid within source-free zone.
where:

$$
\begin{aligned}
& B_{n} \equiv C(n) \cos \left(n \alpha_{n}\right)=2 n-\text { pole NORMAL Term } \\
& A_{n} \equiv-C(n) \sin \left(n \alpha_{n}\right)=2 n-\text { pole SKEW Term }
\end{aligned}
$$

In the US, the $2 n$-pole terms are denoted by $B_{n-1}$ and $A_{n-1}$.
Sometimes, the skew terms are defined without the negative sign, but the above form is the most common now.

## Analytic Functions of a Complex Variable

Any function of the complex variable, $z$, given by

$$
F(z)=U(x, y)+i V(x, y)
$$

is an Analytic function of $\boldsymbol{z}$, if
$\left(\frac{\partial U}{\partial x}\right)=\left(\frac{\partial V}{\partial y}\right)$ and $\left(\frac{\partial U}{\partial y}\right)=-\left(\frac{\partial V}{\partial x}\right)$ Cauchy-Riemann

An analytic function can be expressed as a power series in $z$. This series is valid within the circle of convergence, which extends to the nearest singularity. Analytic function does not depend on $z^{*}$.

## Analyticity of Complex Field

$\left(\frac{\partial U}{\partial x}\right)=\left(\frac{\partial V}{\partial y}\right)$ and $\left(\frac{\partial U}{\partial y}\right)=-\left(\frac{\partial V}{\partial x}\right)$

Cauchy-Riemann Conditions.

Maxwell's equations in source free region:

$$
\nabla \cdot \boldsymbol{B}=0 \Rightarrow\left(\frac{\partial B_{y}}{\partial y}\right)=-\left(\frac{\partial B_{x}}{\partial x}\right)
$$

$$
(\nabla \times \boldsymbol{B})_{z}=0 \Rightarrow\left(\frac{\partial B_{y}}{\partial x}\right)=\left(\frac{\partial B_{x}}{\partial y}\right)
$$

Maxwell's equations $=$ Cauchy-Riemann conditions if we choose: $U(x, y)=B_{y}(x, y)$ and $V(x, y)=B_{x}(x, y)$ Thus, $\boldsymbol{B}(\boldsymbol{z})=B_{y}(x, y)+i B_{x}(x, y)$ is an analytic function of $\boldsymbol{z}$. The analyticity is useful in dealing with 2-D problems in magnetostatics.

## End Fields \& Short Magnets

- The field near the ends of a long magnet, or everywhere in a short magnet, has all three components. The simple 2-D expansion is not valid in these cases. However, if one considers only integrated values of field components, a similar 2-D expansion can be shown to be valid.
- For components of field at a point, a more complex expansion must be used.


## Validity of 2-D Field Expansion



## 3-D Field Expansion

If the field harmonics vary along the axial direction, $Z$ :

| $B_{r}(r, \theta, z)$ | $=\sum_{n=1}^{\infty}\left[B_{n}(z)+\sum_{l=1}^{\infty} \frac{(-1)^{l}(n-1)!(2 l+n)}{2^{2 l} l!(l+n)!} B_{n}^{[2 l]} r^{2 l}\right]\left(\frac{r}{R_{\text {ref }}}\right)^{n-1} \sin (n \theta)$ |
| ---: | :--- |
|  | $+\sum_{n=1}^{\infty}\left[A_{n}(z)+\sum_{l=1}^{\infty} \frac{(-1)^{l}(n-1)!(2 l+n)}{2^{2 l}!(l+n)!} A_{n}^{[2 l]} r^{2 l}\right]\left(\frac{r}{R_{r e f}}\right)^{n-1} \cos (n \theta)$ |

$$
\begin{aligned}
B_{\theta}(r, \theta, z)= & \sum_{n=1}^{\infty}\left[B_{n}(z)+\sum_{l=1}^{\infty} \frac{(-1)^{l} n!}{2^{2 l} l!(l+n)!} B_{n}^{[2 l]} r^{2 l}\right]\left(\frac{r}{R_{\text {ref }}}\right)^{n-1} \cos (n \theta) \\
& -\sum_{n=1}^{\infty}\left[A_{n}(z)+\sum_{l=1}^{\infty} \frac{(-1)^{l} n!}{2^{2 l}!(l+n)!} A_{n}^{[2 l]} r^{2 l}\right]\left(\frac{r}{R_{\text {ref }}}\right)^{n-1} \sin (n \theta)
\end{aligned}
$$

where the index [2l] denotes $(2 l)^{\text {th }}$ derivative with respect to $z$. If integral values are considered between $Z_{1}$ and $Z_{2}$ such that all derivatives are zero at the ends, then the above expression reduces to the 2-D expansion.

## Interpretation of Harmonics

$B_{n+1}($ European $)=B_{n}(\mathrm{US})=\left.\frac{R_{r e f}^{n}}{n!}\left(\frac{\partial^{n} B_{y}}{\partial x^{n}}\right)\right|_{x=0 ; y=0} n \geq 0$
$A_{n+1}($ European $)=A_{n}(\mathrm{US})=\left.\frac{R_{r e f}^{n}}{n!}\left(\frac{\partial^{n} B_{x}}{\partial x^{n}}\right)\right|_{x=0 ; ; y=0} n \geq 0$
$B_{y}=$ Constant $\Rightarrow$ Dipole Only
$\left(d B_{y} / d x\right)=$ Constant $\Rightarrow$ Dipole plus Quadrupole and so on ...

## Examples of Harmonics



## Normalized Coefficients: Multipoles

- The coefficients $B_{n}$ and $A_{n}$ denote the absolute strength of the $n$-th harmonic, and are thus a function of the magnet excitation.
- The variation in the shape of the field as a function of excitation is best described using coefficients normalized by a suitable reference field, often chosen to be the amplitude of the most dominant term in the harmonic expansion. The normalized coefficients are also referred to as multipoles.


## Normalized Coefficients: Multipoles

$$
\begin{aligned}
B_{y}+i B_{x} & =\sum_{n=n_{0}}^{\infty}\left[B_{n}+i A_{n}\right]\left(\frac{x+i y}{R_{\text {ref }}}\right)^{n-n_{0}} ; \begin{array}{l}
n_{0}=0: \text { US } \\
n_{0}=1: \text { European }
\end{array} \\
& =B_{r e f} \sum_{n=n_{0}}^{\infty}\left[b_{n}+i a_{n}\right]\left(\frac{x+i y}{R_{r e f}}\right)^{n-n_{0}} ; \text { where } \\
b_{n} & =B_{n} / B_{r e f} ; \quad a_{n}=A_{n} / B_{r e f}
\end{aligned}
$$

For a $2 m$-pole magnet, $B_{\text {ref }}$ chosen as $\left|B_{m}+i A_{m}\right|$
$\left(b_{n}, a_{n}\right)$ independent of current: LINEAR SYSTEM
$\left(b_{n}, a_{n}\right) \times 10^{4}=$ Normal \& Skew Multipoles in "UNITS"

## Properties of Harmonics

- The Normal and Skew harmonics represent coefficients of expansion in a power series for the field components.
- The harmonics allow computation of field everywhere in the aperture (within a circle of convergence) using only a few numbers.
- These coefficients obviously depend on the choice of origin and orientation of the coordinate system. Measured harmonics, therefore, often need to be centered and rotated.


## Field in a Non-circular Aperture

The 2-D field expansion in a harmonic series is valid only within the circle of convergence, which extends from the origin to the nearest current element or a magnetic material ("singularity").

For non-circular apertures, a single series expansion may not cover the entire "source-free region", even though the complex field $B_{y}+i B_{x}$ is an analytic function of $(x+i y)$ throughout the aperture. One can circumvent the problem by defining several series expansions, each centered at a different origin.

## Field in a Non-circular Aperture



By having a significant overlap between the various circles of convergence, one can verify the integrity and accuracy of data by comparing results in the overlap regions.

## Calculation of Field Outside Convergence Radius

- The field at any point $(x, y)$ can be computed from the normal and skew harmonics measured at ( $x_{0}, y_{0}$ ) using:

$$
B_{y}(x, y)+i B_{x}(x, y)=\sum_{n=0}^{\infty}\left(B_{n}+i A_{n}\right)\left(\frac{\left(x-x_{0}\right)+i\left(y-y_{0}\right)}{R_{r e f}}\right)^{n}
$$

- For accurate calculations of field, the origin $\left(x_{0}, y_{0}\right)$ should be chosen such that the field point $(x, y)$ is as close as possible, and is well within the circle of convergence defined by the pole tips.
- In special situations, such as when the higher order terms are identically zero, convergence of the series may not be a problem, and it may be possible to calculate the field outside the radius of convergence using the same ( $B_{n}, A_{n}$ ).

Error Due to Extending Radius of Pos. 3 Practical Example: SD1717 (1 GeV) (SNS Dipole)



## The Vector Potential

Scalar potential approach does not provide a relationship between the currents and the field.

From Maxwell's equations:
$\nabla . \mathbf{B}=0 ; \quad \therefore \mathbf{B}=\nabla \times \mathbf{A} \quad \mathbf{A}$ is called the Vector Potential

$$
\nabla \times \mathbf{B}=\mu_{\mathbf{0}}(\nabla \times \mathbf{H})=\mu_{\mathbf{0}} \mathbf{J} \quad \text { In "free space", } \mathbf{B}=\mu_{0} \mathbf{H}
$$

$\nabla \times \mathbf{B}=\nabla \times(\nabla \times \mathbf{A})=\mu_{0}(\nabla \times \mathbf{H})=\mu_{0} \mathbf{J}$
$\nabla^{2} \mathbf{A}=-\mu_{0} \mathbf{J}$
Poisson's Equation

$$
\mathbf{A}(\mathbf{r})=\left(\frac{\mu_{0}}{4 \pi}\right) \int \frac{\mathbf{J}\left(\mathbf{r}^{\prime}\right)}{\left|\mathbf{r}-\mathbf{r}^{\prime}\right|} \mathrm{d} \mathbf{r}^{\prime}
$$

## Summary

- The 2-D field , away from the ends, in the aperture of a typical accelerator magnet, can be described by a simple power series, valid within a circle extending to the nearest current source or magnetic material.
- A similar 2-D expansion is also valid for 3-D fields if one considers only integrated values of the field components such that there is no axial variation at the boundaries of the integration interval.


## Summary (Contd.)

- The expansion coefficients may be interpreted as spatial derivatives of the field components.
- The expansion coefficients, or harmonics, depend on the choice of coordinate frame. This demands a careful description of the frame when quoting results of measurements. Similarly, users of the data also need to pay close attention to the coordinate definition.


## Summary (Contd.)

- The complex field, $\boldsymbol{B}(z)=B_{y}+i B_{x}$, is an analytic function of the complex variable, $z$.
- For non-circular apertures, one can describe the field in the entire aperture by defining several series expansions centered at different points in the aperture (analytic continuation).
- Scalar potential approach is unsuitable for establishing a relationship between the current and the field. A vector potential approach is more general.

