

D1 Field Quality

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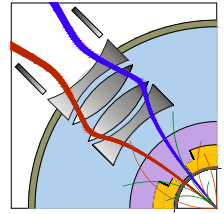
BNL

APUL CD1 Director's Follow-up Review

2-3 November 2009



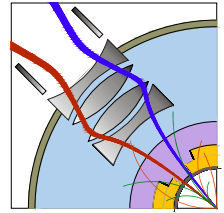
Overview



- Issues, challenges and strategies for obtaining the required field quality
- Coil cross-section
 - Flexible but no change in basic cross-section over existing DX
- Yoke design to minimize harmonics while meeting other requirements
 - Yoke design is complete, minor iterations can still be accommodated
- Alternate coil End Design
 - New end design with ROXIE is complete, minor iterations possible
- Lorentz Forces between the two LDX coldmasses
 - It's a small effect
- Response to the revised field quality requirements from CERN
 - New requirements are more demanding
- Summary



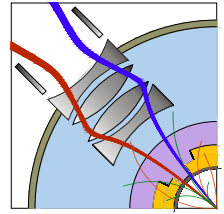
Issues



- In terms of field quality expectations in APUL D1 dipoles, we should benefit from the fact that similar 180 mm dipoles have been built and tested before for RHIC insertion region. Field quality in those 13 RHIC DX dipoles has been measured and except for a few lower order harmonics, it is generally acceptable for LHC upgrade.
- However, when looked in detail, the situation is not so straight forward.
- For good field quality and correct pre-stress, we generally want coil size to be within 50 micron or less of the design. However, for a 71 turn coil it is already exceeded by about an order of magnitude by the cumulative cable tolerances of +/- 6 microns (in RHIC DX, we had to increase number of turns to 71 from original design of 70).
- Since the iron yoke (both geometry and material) is different; saturation-induced allowed harmonics will be different. Moreover, Lorentz force-induced harmonics could be different. In addition, there are skew harmonics because of non-symmetric placement of coldmass in cryostat.



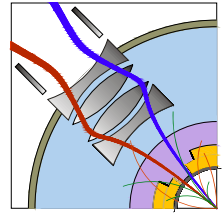
Challenges and Strategy



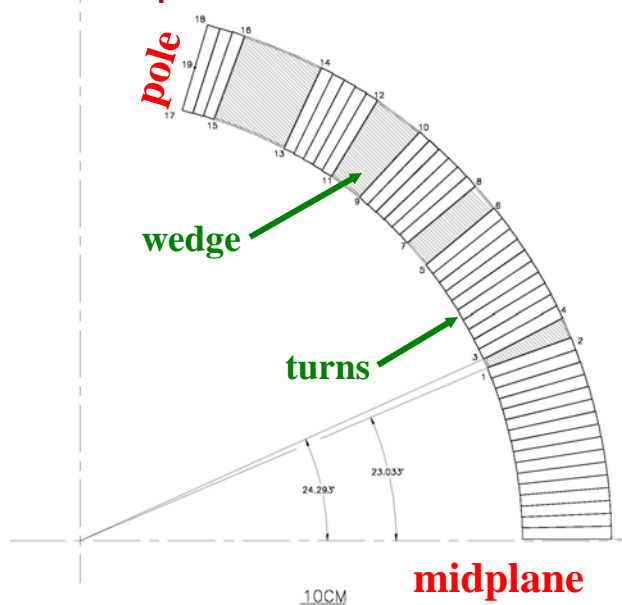
- Field quality in the first magnet (even that based on an earlier design) could be off for a variety of reasons. For achieving 10^{-4} field errors, the devil is in the details.
- Cross-section iterations is the traditional method for assuring good field quality.
- **However, these iterations consume significant time and cost.**
- Eliminating them, as proposed for the D1 magnets for APUL, is a good example of “Value Engineering”. Absence of them obviously creates some risk.
- Thus the main field quality challenge of the program is the absence of building any **“proto-type or pre-production magnet”** before the start of production
 - The first magnet should be usable in the machine (or at most be spare).
 - No planned change in iron or coil design from beginning to end.
 - Only minor adjustments are allowed/planned to control the field quality through the production (from the first magnet to the last magnet).
- The key to “risk mitigation” is a “flexible design” plus careful and thoughtful planning.
- **This presentation will outline our strategy based on the past successful experiences in various RHIC magnets. We are confident that it can be done (again).**



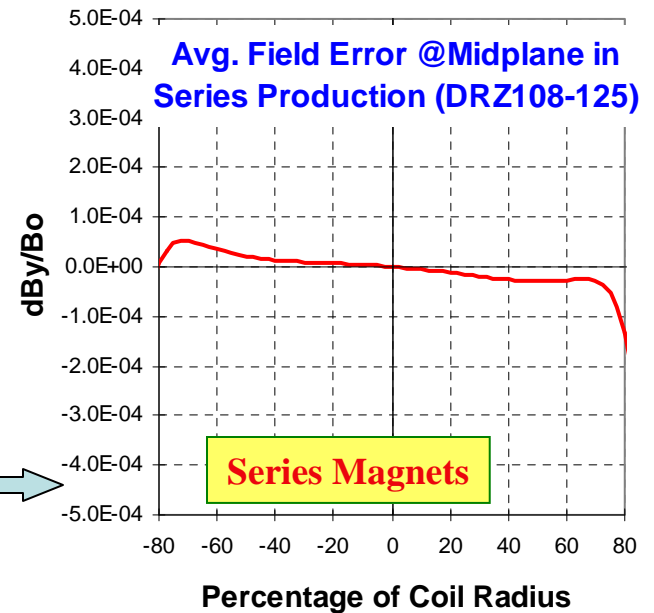
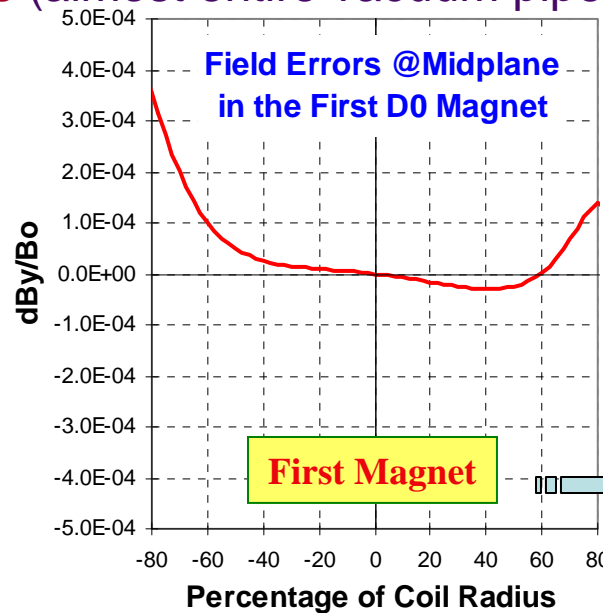
Plan for Flexible Coil Cross-section in APUL D1 (Do the same as done in 100 mm RHIC IR Dipole)



- In 100 mm RHIC IR dipoles, we developed techniques that were simple to implement but yet power enough to produce the **very first magnet** with accelerator grade field quality in (field errors ~ 1 part in 10^4 up to 60% coil radius).
- The flexibility was obtained by starting with more than minimum midplane and pole shims. Then adjustment in the size of them allowed an easy way of tuning field harmonics during the production without changing the actual coil cross-section.
- It resulted in very good field quality magnets – we achieved average error < 1 part in 10^4 up to $\sim 80\%$ of coil radius (almost entire vacuum pipe).



RHIC 100 mm D0

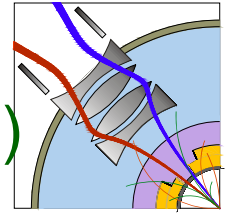


Much faster and much cheaper than conventional iterations

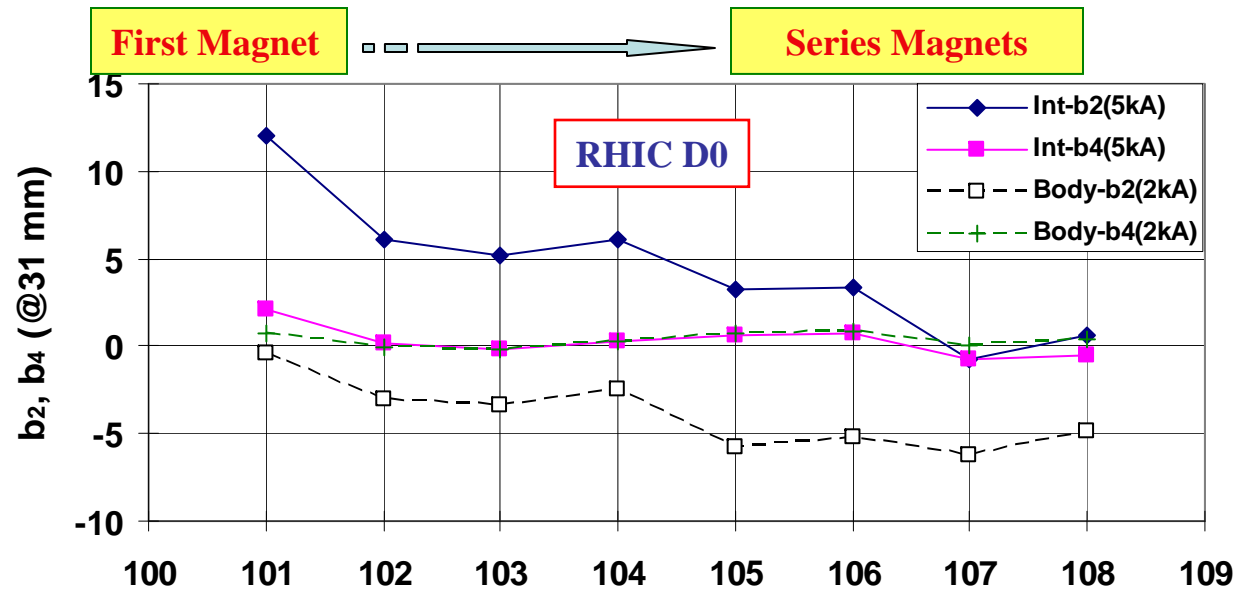
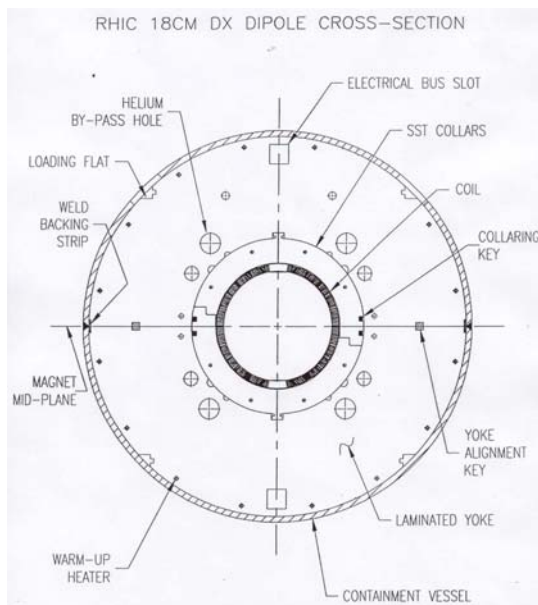


Plan for Flexible Yoke Cross-section in APUL D1

(Do similar to was done in 100 mm RHIC IR Dipole)



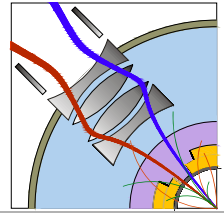
- Have extra strategically located saturation control holes in the yoke lamination and fill them up with iron rods as needed.
- This takes care of both saturation-induced harmonics (culprit iron) and Lorentz force induced harmonics (culprit coil, particularly if there is a small radial gap of ~50 micron or so between coil & collar, built-up due to normal tolerances in parts).
- Final result of this adjustment is a smaller change in harmonic as a function of current, independent of who the culprit is.



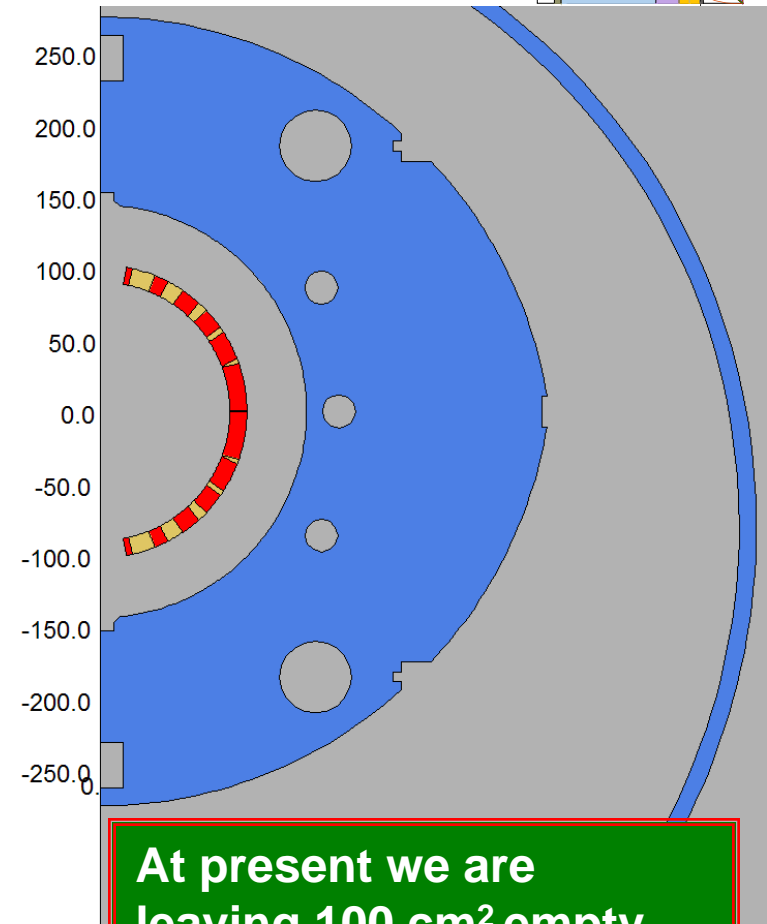
Much faster and much cheaper than conventional iterations



New D1 Yoke Design (oblate)



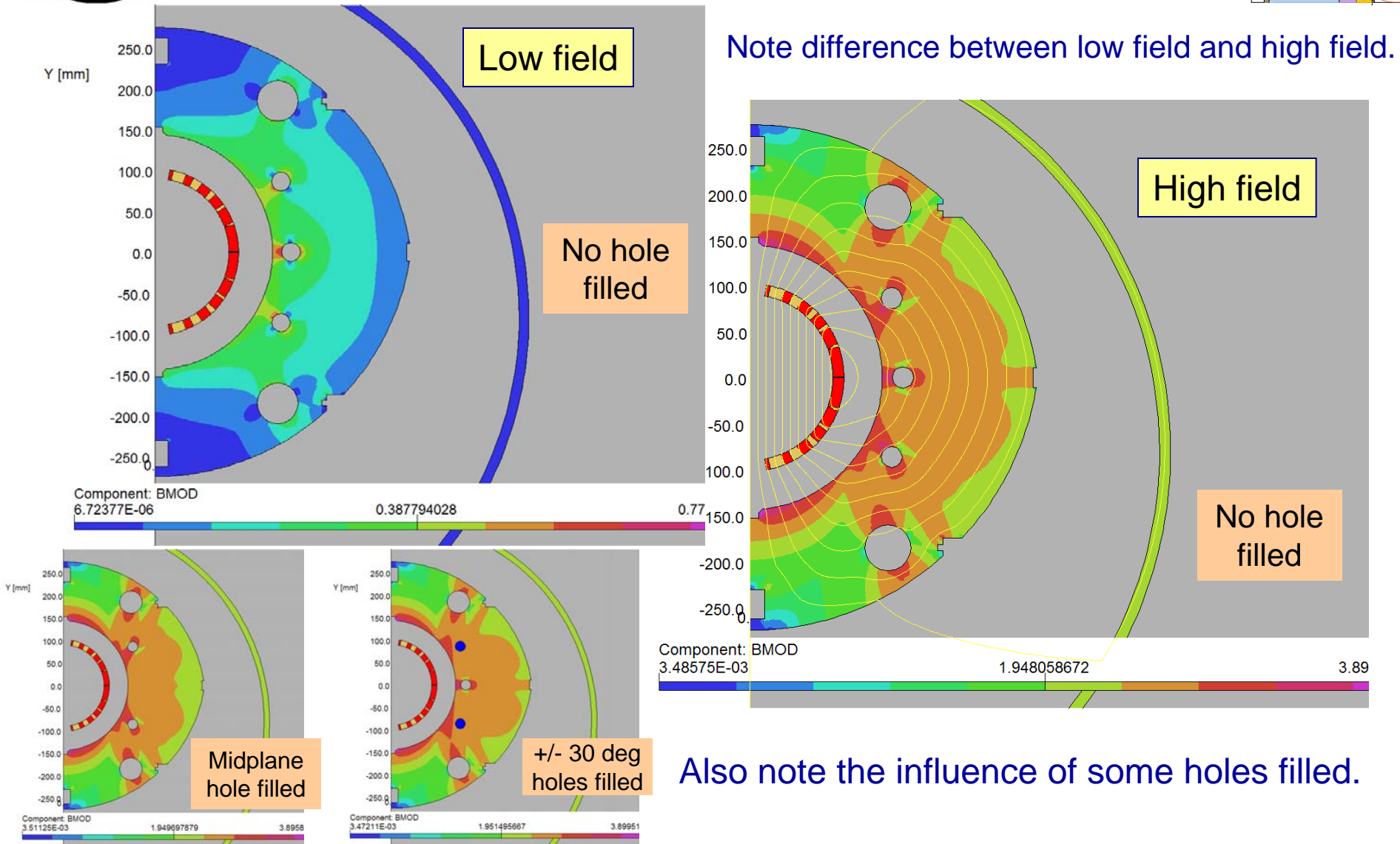
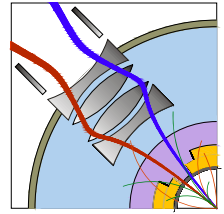
- Iron saturation (plus Lorentz force) induced harmonics (normal and skew due to cryostat) are controlled with the help of saturation control holes
- These holes are in addition to the helium holes.
- As such the three holes shown near the yoke inner radius are adequate to obtain low computed change in harmonics as a function of current.
- However, we have additional tuning flexibility by allowing the three holes to be partially filled with the low carbon steel (magnetic) rods.
- The length of each rod will be determined after the initial magnetic measurements.
- These holes and rods effectively facilitate the iteration of yoke without changing the geometry.
- It also provides the capability fine turning.



At present we are leaving 100 cm² empty space in yoke for helium. It could be increased up to ~20%, if required.



Saturation Control Holes are Used to Force Uniform Magnetization of Iron Near the Yoke Inner Surface



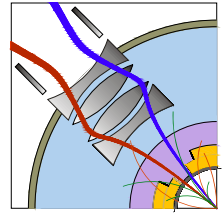
Note difference between low field and high field.

Also note the influence of some holes filled.



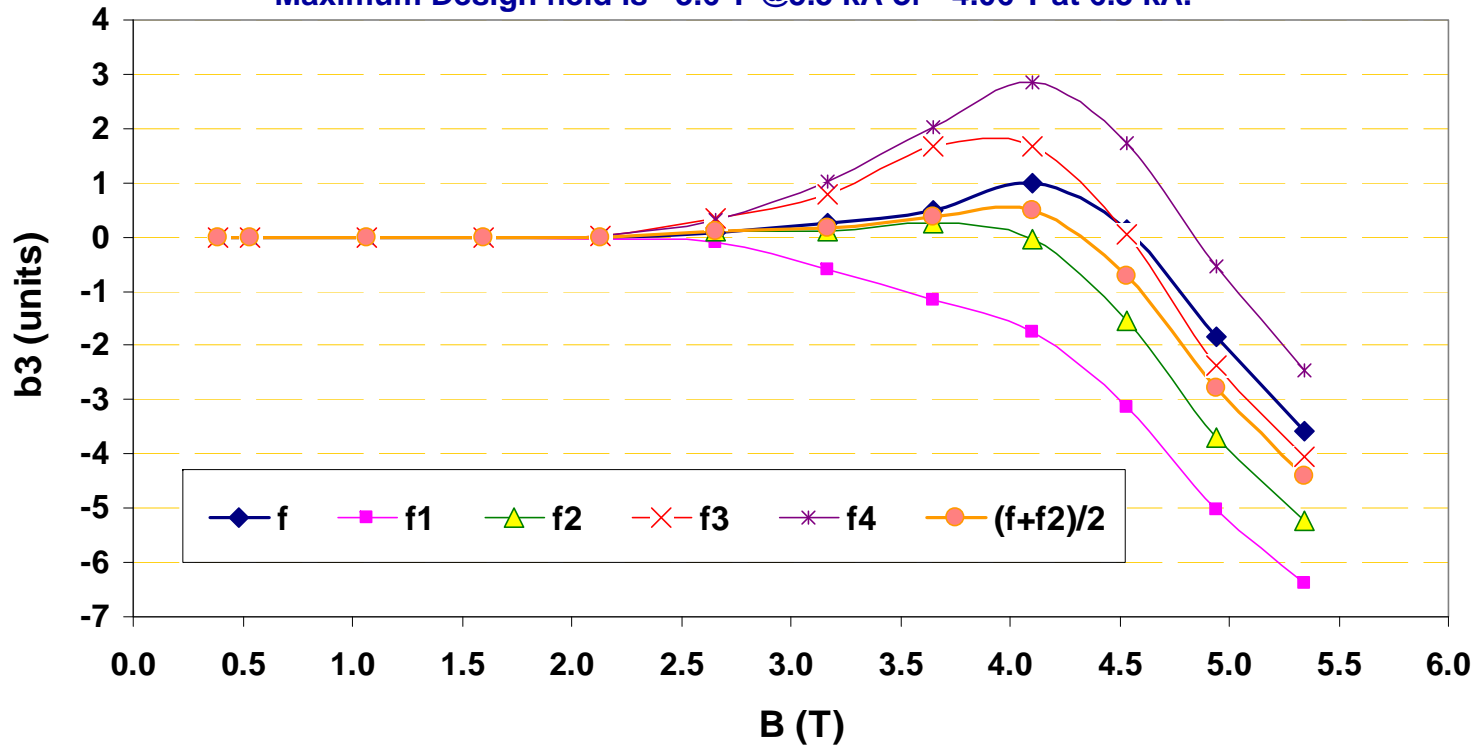
Computed Field Dependence of b_3

(with and without holes filled with iron rods)



Sextupole harmonic with & without various iron rods

Maximum Design field is ~3.6 T @5.5 kA or ~4.06 T at 6.3 kA.



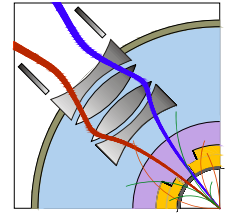
- There is a clear ability to change the variation in saturation induced harmonic in either direction.
- Holes cover a reasonable range of expected variations.

$(f+f_2)/2$ is one hole filled with half length rod

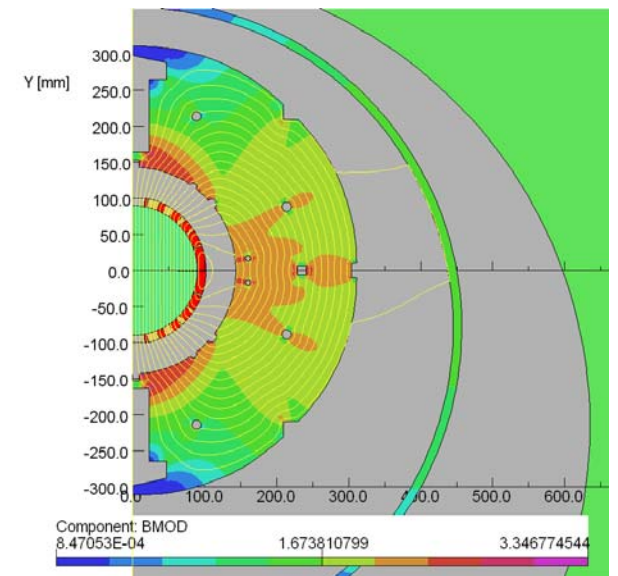
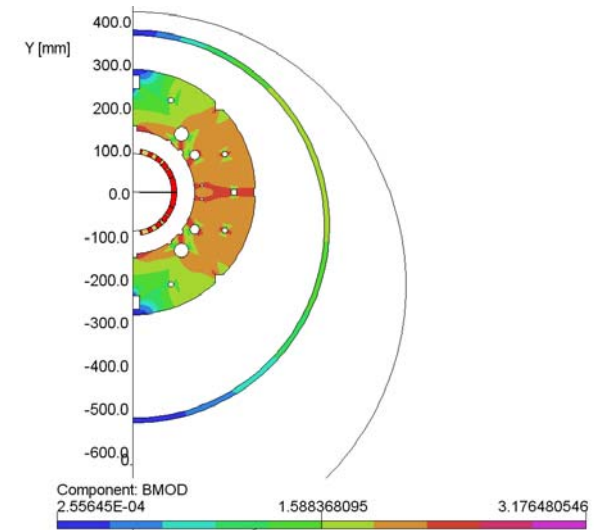
Saturation induced b_3 in the initial design was ~3 units.



Skew Quad (a_2) Harmonic at High Fields

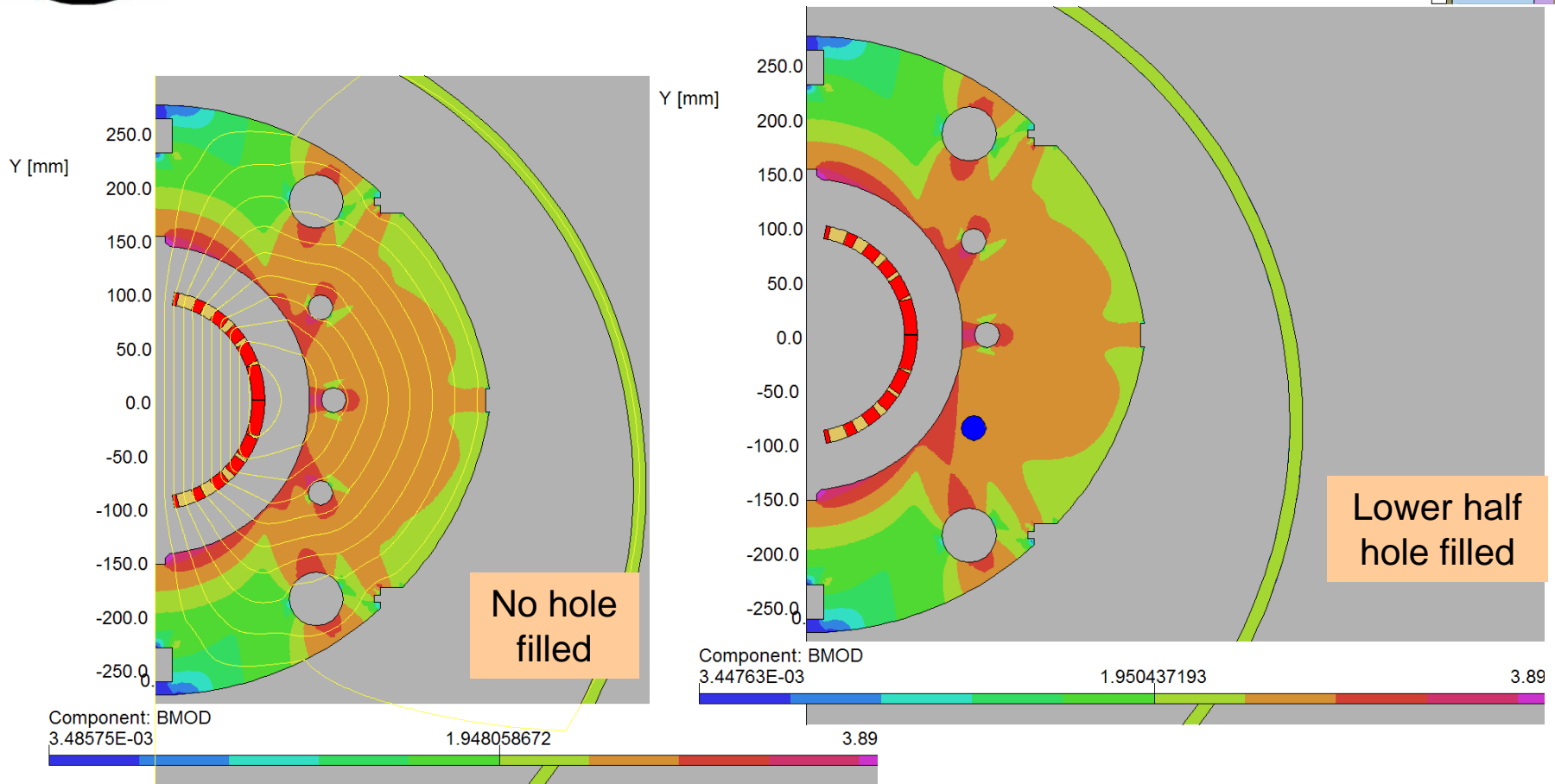
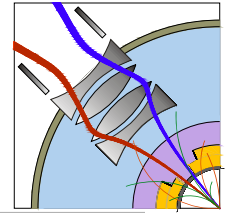


- Non symmetric vertical placement of the coldmass inside the cryostat creates skew quadrupole harmonic (a_2) at high fields when the flux leaks out of the yoke.
- In RHIC dipoles, this was partly compensated by placing heavier yoke packs in the lower side.
- We could use a similar technique here.
- Additional asymmetry can also be created with some strategically located holes in a symmetric yoke and then partially filling one or more of them in the lower yoke half only.
- We find that this asymmetry to compensate for the proximity of the cryostat to the upper half is a simple, powerful and a flexible technique.
- We propose to use this in APUL.





Change in Yoke Saturation by Filling Saturation Control Hole in Lower Half Only

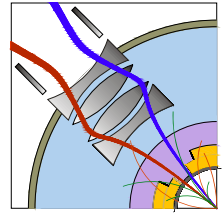


Filling of hole in lower half by low carbon steel magnetic yoke can compensate for the proximity of the cryostat to the upper half.



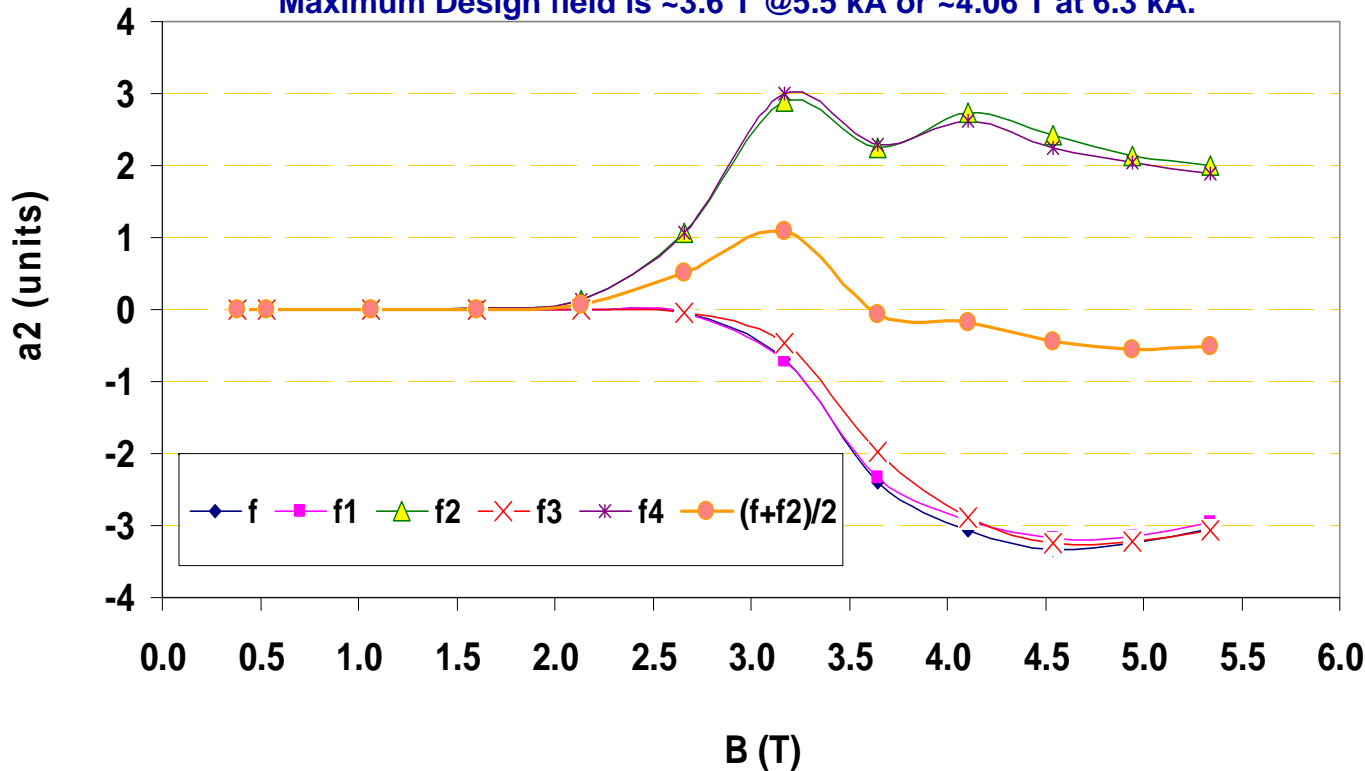
Computed Field Dependence of a_2

(with and without holes filled with iron rods)



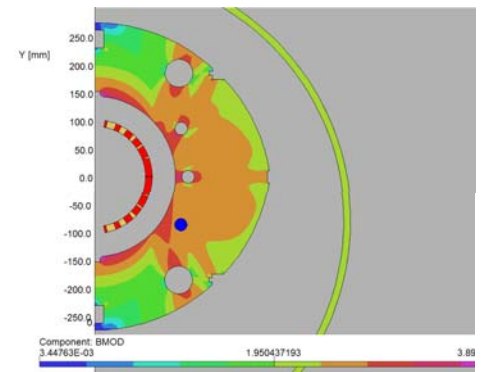
Skew quad harmonic with and without iron rods

Maximum Design field is ~3.6 T @5.5 kA or ~4.06 T at 6.3 kA.



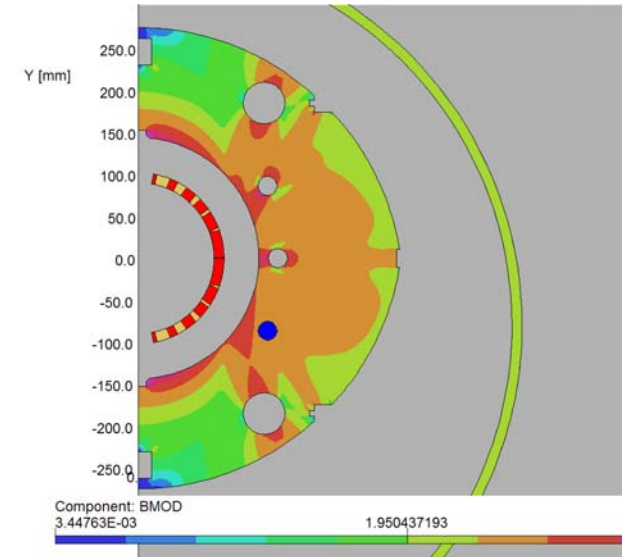
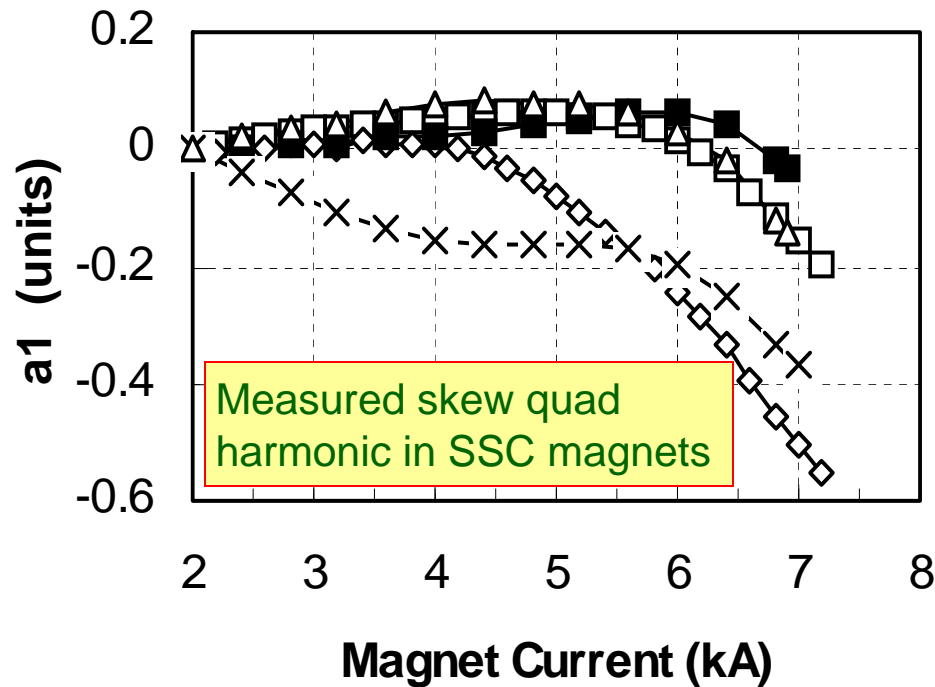
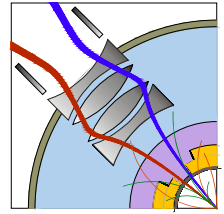
$(f+f2)/2$ is one hole filled with half length rod

- There is a clear ability to change the variation in saturation induced harmonic in either direction.
- Holes cover a reasonable range of expected variations.
- Location and size of the hole may be optimized to reduce intermediate peak.





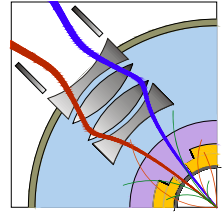
Ability of Saturation Control Hole to Reduce Magnet to Magnet Variation in Saturation



- In SSC magnets, we observed a significant magnet to magnet variation in saturation induced skew quad harmonic between various magnets.
- Length of the magnetic rod can be adjusted after the measurements to reduce this magnet to magnet variation.

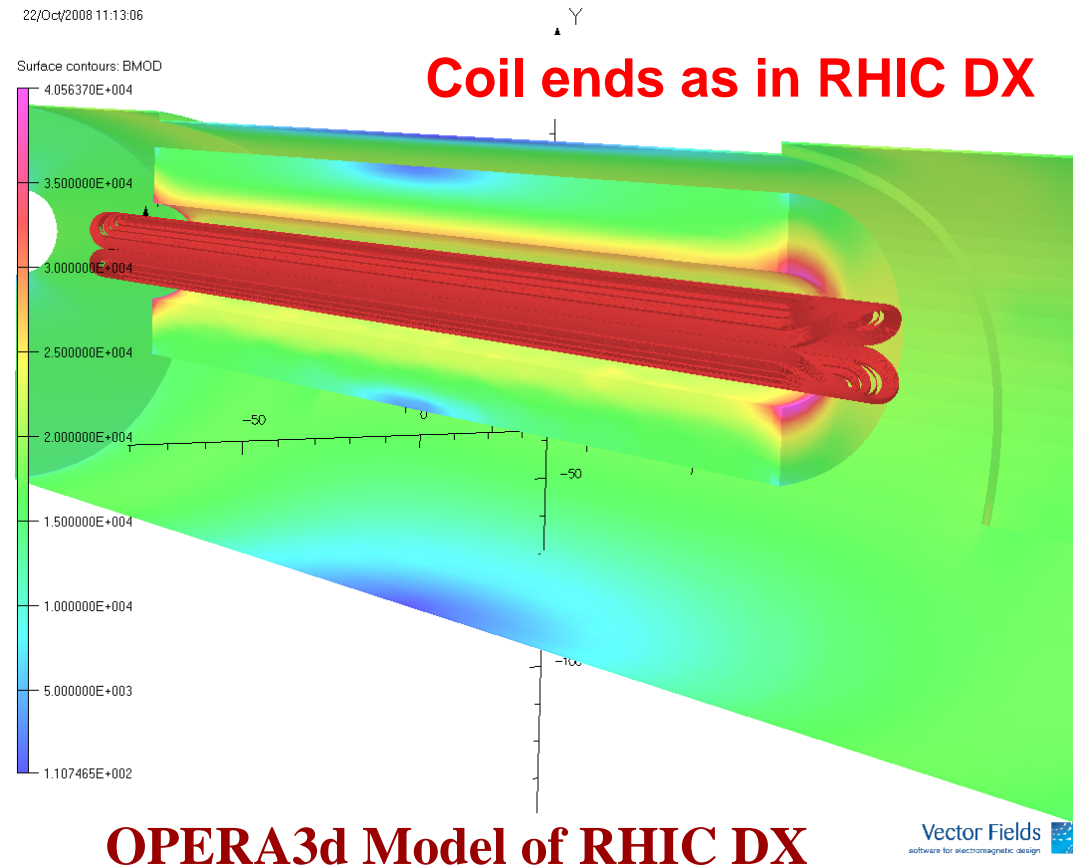


Coil Ends



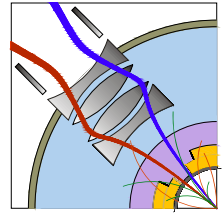
The goal of this exercise is to develop an alternate end design to determine/compare by computer modeling the new improved ends with the original RHIC DX coil ends (Mike Anerella).

- The layout of the blocks and individual turns of coil ends is optimized using “differential geometry” method in ROXIE 10.1 (similar to the method used in program BEND) to improve the mechanical layout of the turns.
- The size and location of the end spacers is then optimized with ROXIE to obtain a good magnetic design with low end harmonics.



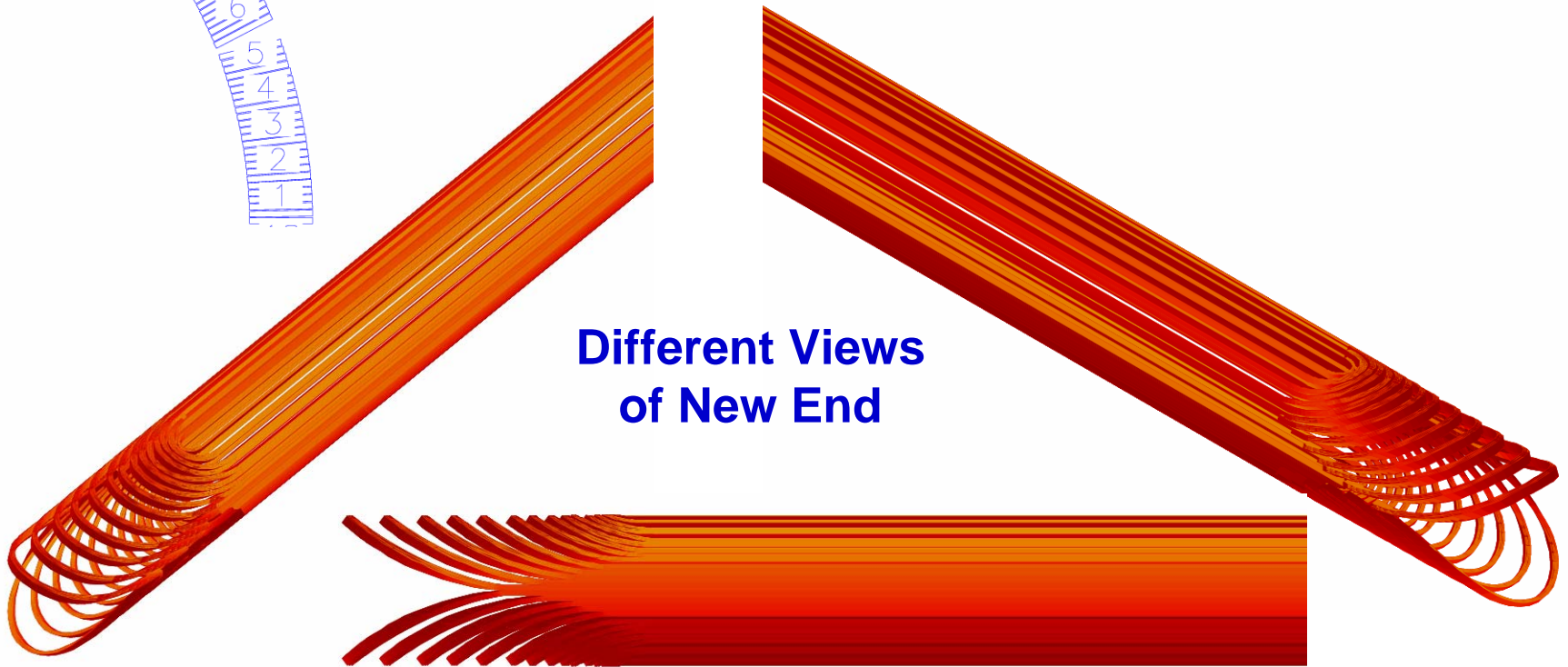


New DX Ends Optimized with ROXIE



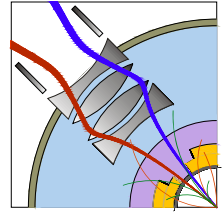
- Large blocks (blocks with large number of turns in cross-section) are divided such that most have five turns or less
- Differential geometry method is used for mechanical optimization
- Size of some spacers is optimized to obtain low end harmonics
- These ends are now being mechanically analyzed with ANSYS

**Different Views
of New End**





Magnetic Forces Between the Two Coldmasses

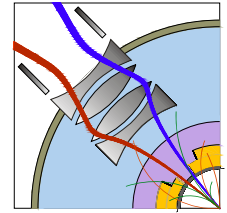


- At one stage there was a concern about the magnetic interaction between the two coldmasses placed in close proximity.
- If the two coldmasses are very close, then the leakage field from the one on other would create additional magnetic force on each magnet.
- We considered the case when the space between the two end plates was only a few centimeters (remember, there is a much larger space between the actual coil ends because of the end saddles and endplates inside).
- The computed value of force (based on rough calculations) was small : ~ 4 kN per end. This is not surprising as the leakage field is relatively small.
- Moreover, since then the spacing between the two coldmasses has now been significantly increased (~ 0.5 meter).



APUL D1 Error Table

(as presented in the last meeting and sent to CERN earlier)



LE + Body + NLE + space + NLE + Body + LE

LHC/BNL/D1 Version (1c)						
Expected values of integral harmonics at 2000 A in 180 mm aperture D1 dipoles (consisted of two LDX):						
(assumes one LDX coldmass with 2 warm and 2 cold measurements to be used for tuning of INTEGRAL geometric and saturation harmonics)						
***** Reference Radius is 40 mm *****						
Harmonics in units (European notation; n=3 is sextpole)						
[<bn> = mean, d(bn) = uncertainty in mean]						
[sig(bn) = sigma for bn, sig(an) = sigma for an]						
n	<bn>	d(bn)	sig(bn)	<an>	d(an)	sig(an)
2	0.0	0.5	0.6	0	2	2
3	0	2	1	-1	2	0.3
4	0.0	0.2	0.1	0.0	0.3	0.4
5	0.0	1.0	0.1	0.0	0.1	0.05
6	0.0	0.05	0.02	0.0	0.10	0.05
7	-0.2	0.3	0.02	0.0	0.02	0.02
8	0.000	0.002	0.003	0.0	0.02	0.01
9	-0.05	0.100	0.003	0.0	0.01	0.001
10	0.00	0.001	0.001	0.0	0.005	0.001
11	-0.02	0.020	0.0003	0.0	0.0003	0.0002
12	0.00	0.0001	0.0001	0.0	0.0002	0.0002
13	0.01	0.010	0.0001	0.0	0.0001	0.0001
14	0.00	0.0001	0.0001	0.0	0.0001	0.0001
n	<bn>	d(bn)	sig(bn)	<an>	d(an)	sig(an)

Based on the beam dynamics studies, CERN has requested us to reduce these harmonics by a factor of two

Both systematic and random

These are associated low field harmonics

Following harmonics may show significant variation as a function of current (as compared to the uncertainty in mean)

Persistent current changes are incorporated in <b3> and saturation in d(b3) and d(a2)

I (A)	<b3>	d(b3)	sig(b3)	<a2>	d(a2)	sig(a2)
360	-5	2.5	1.1	0	2	2
1000	-1	2	1	0	2	2
2000	0	2	1	0	2	2
4000	0	2	1	0	2.5	2.2
5600	0	2	1	0	2.5	2.5
6500	0	2.5	1.0	0	3.0	3.0
7500	0	3.0	1.1	0	3.0	3.5

Reference Radius is only 40 mm for a coil Radius of 90 mm.

Expect smaller higher order harmonics

LHC/BNL/D1 Version (1c)

Ramesh Gupta, July 6, 2009

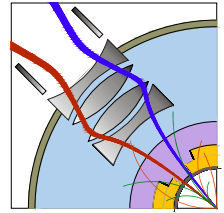
Maximum Design field is ~3.6 T @5.5 kA or ~4.06 T at 6.3 kA.

D1 Field Quality - Ramesh Gupta

Slide No. 17



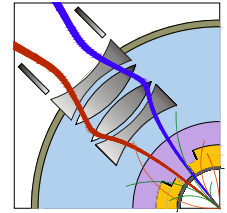
Response to the Requested Change in Field Error Table



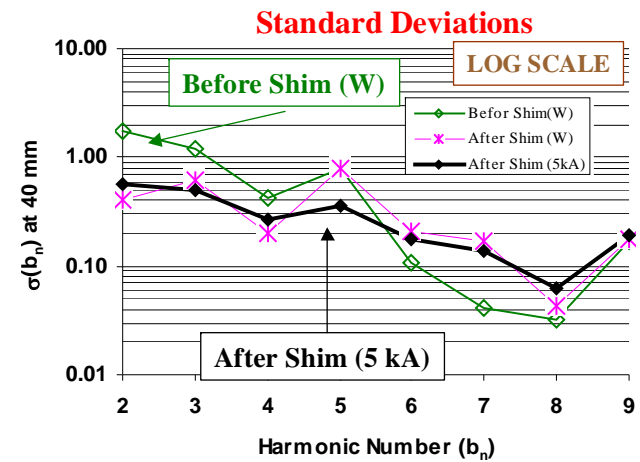
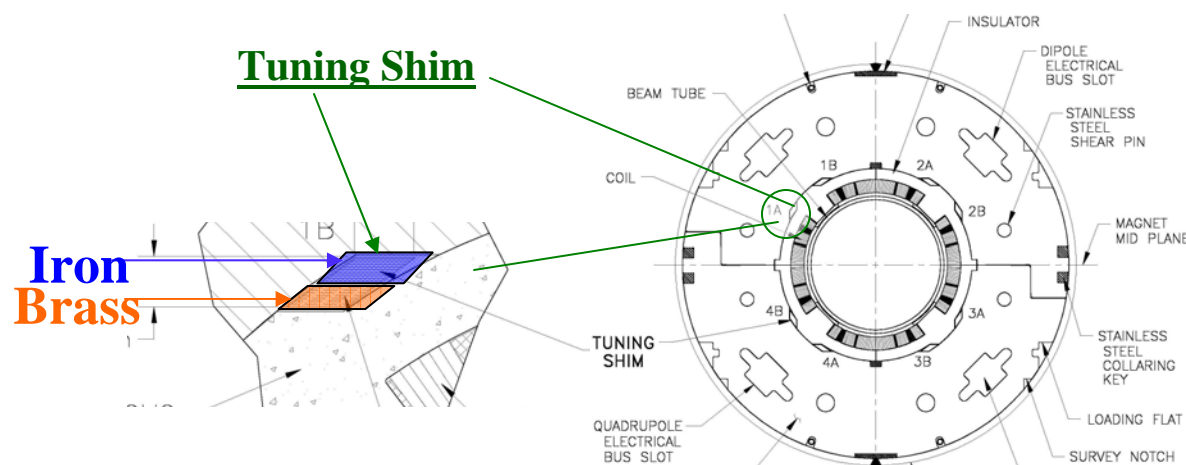
- Background on Error Table
 - Earlier version of BNL error table was primarily based on RHIC DX and other magnets (along taking credit for certain harmonic tuning)
 - Generally, doing better means some additional steps will be required
- Systematic Errors
 - We have worked on the design to reduce systematic errors (earlier slides in this presentation related to harmonic tuning)
- Random Errors
 - These are associated with the magnet construction
 - Since we are not planning to change construction methods, as such no significant change should be expected
 - However, we have looked at the number of ways to reduce random errors. Next few slides will outline current thinking and work in progress



Approach #1 : Tuning Shims to Compensate for the Construction Errors

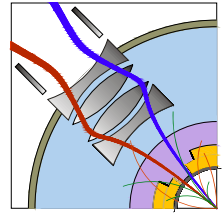


- We considered something equivalent to tuning shims (as used in RHIC 130 mm high field quality interaction region quads to compensate for the normal construction errors)
- However, that would have significant impact on the cost (additional work and additional tests)
- Since we do not see attractive cost to benefit ratio, that approach would not be used





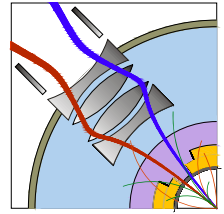
Approach #2 : Use Unique Configuration of the D1 Magnet



- Each D1 is consisted of two LDX coldmasses. CERN requires minimization of the integral field errors (beam is forgiving us on the local variations).
- Let us consider separately the request to reduce (a) random skew quadrupole and (b) random sextupole harmonics, both by a factor of two.
- Skew quad error harmonic changes sign if a dipole is rotated by 180 degree.
- We are examining building magnets in such a way that the relative orientation between the two neighboring coldmasses is determined only after the magnetic measurements and before two LDX are joined to make a D1.
- This will reduce skew quad by at least a factor of two (least reduction if one has a large magnitude and other is zero). This would reduce systematic too.
- Random sextupole error can be reduced by sorting of LDX coldmasses.
- However, this may have an impact on the schedule as the two LDX coldmasses can not be joined to make one D1 as soon as they are ready. One would perhaps need a pair of LDX coldmasses in hand to sort.
- This sorting should further reduce skew quad harmonic as well.



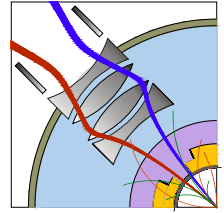
Status of Our Ability to Meet the Field Error Table (as specified by CERN)



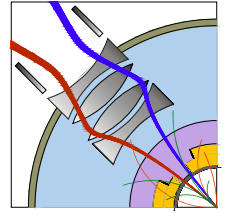
- With the flexible coil and flexible yoke design, we should be able to meet most systematic harmonic tolerances as requested by CERN. It might be tight in a couple of cases but are not outside the realm of possibility.
- CERN has requested random errors in some cases to be less than it was in RHIC DX. We should be able to meet them with the sorting requested.
- CERN has requested to reduce the systematic value of integral skew sextupole over what it was in RHIC. That large value was related to the leads. We should be able to reduce that with a careful design of lead connections between the two coldmasses.
- CERN has also mentioned that it is a matter of increasing the strength of correctors, if some harmonics are not met.
- Overall we are in a reasonable shape (but not in a too comfortable zone).



Summary



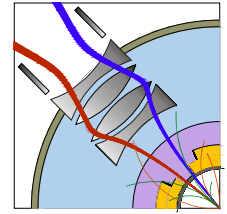
- A significant progress has been made since the last review.
- The yoke and coil designs are nearly complete (some adjustments are still possible based on various needs).
- Strategies have been developed to meet tighter field quality specifications from CERN on certain harmonics.
- We are adopting a value engineering approach to save on cost and schedule by eliminating customary magnet iterations.
- The main field quality challenge of this program is to assure a good field quality in production despite “NO proto-type or pre-production magnets”.
- With a flexible design, past experience and proper planning, we are confident to be able to do it again as we did in RHIC.



Backup Slide(s)



Background on Oblate Yoke Option



- Oblate yoke has now been successfully used in LHC D2/D4
- This saved significant effort and money by allowing us to use standard LHC cryostat and posts.

From MT15 Paper

The proposed oblate-shaped yoke also offers a way to reduce the overall cryostat size in future magnets. In most magnets, the horizontal size is determined by the magnetic and mechanical designs and the vertical size is determined by the heat leak budget and post design. The two are then added to determine the overall size. In modifying the circular yoke shape to an oblate shape, yoke iron is removed from the vertical plane, as this material does not contribute to the magnetic and mechanical design. The vertical space, thus saved, can be utilized by the post and thermal shielding, reducing the overall size. The validity of this design will be tested in the first model magnet to be built at BNL prior to the production run of the LHC insertion magnets.

BNL/LHC MAGNETS

