

A Proposed Value Engineering Design for B1ApF

Ramesh Gupta

January 7, 2025

<<< SPOILER ALERT >>>

PBL/BNL team is carrying out a Phase II STTR, "*A new medium field superconducting magnet for the EIC***". One preliminary outcome:**

➢ **Present design of EIC IR dipole B1ApF based on the Rutherford cable could be replaced by a 4-layer direct wind optimum integral dipole !**

Evaluate the overall impact on cost and schedule - value engineering

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PBL/BNL Phase II STTR Proposal

\checkmark Answer: Yes. Quench performance remains excellent

These two are significant achievements for a Phase I award (demo in <1 year)

Question for Phase II: Will this excellent performance of the "Direct Wind" technology continue to higher fields and larger bore magnets, e.g., as needed for EIC and other applications?

Ramesh Gupta for PBL/BNL Team, FY24 NP SBIR/STTR Phase II Exchange Meeting, Aug 14, '24

Project Title: A new medium field superconducting magnet for the EIC

Waxahachie, TX 75167-7279

Particle Beam Lasers, Inc.

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Topic No. 37: **Nuclear Physics Accelerator Technology**

Subtopic (g): Magnet Development for Future Electron-Ion Colliders (EIC)

Grant Award Number: DE-SC0021578

Task 8: Evaluation of the Optimum Integral Design for Other Applications: The optimum integral design, once demonstrated for EIC IR dipole BOApf can be applied to other EIC magnets (dipoles and quadrupoles) to reduce the maximum field required for the same integral field in the allocated length of the magnet.

Company Name:

Principal Investigator:

Address:

Overview

Optimum Integral Design:

• **Why, What, Where used?**

PBL/BNL STTR on the Direct Wind Optimum Integral Dipole B0ApF (NOT B1ApF):

- **What was demonstrated in Phase I**
- **What has been demonstrated so far in Phase II**
- **Status of the Phase II for B0ApF (all 12 layers wound, to be discussed briefly)**

Evaluation of the Optimum Integral Dipole for B1ApF under STTR

- **Initial results… Very Attractive! … Why so?**
- **Sanity check – are these results too good to be true? Are methods validated?**

Possible future work under EIC funding B1ApF+ (if go ahead is received)

Summary Eink to more information on the optimum integral dipole: <https://wpw.bnl.gov/rgupta/optimum-integral/>

A two-step process of designing magnets: Step 1: Optimize coil cross-section to obtain cosine theta like distribution (spread out turns): $I(\theta) = I_o$. cos(n θ) **Conventional Design Approach**

➢ **This limits the number of turns in straight section**

Step 2: Optimized ends to reduce integral harmonics, and to reduce peak field on the conductor

➢ **This spreads out turns in the ends, making the ends longer, and reducing the field per unit length**

Motivation to the Integral Design Concept (AGS corrector: Length = 300mm, diameter=182.8 mm)

- **In such a short dipole, there is little to no flat-top along the axis (so called body of the magnet).**
- **Since the axial field profile is not going to see "body" and "ends" separately, why not combine the two together for an integral design optimization?**
- **Can that be more efficient?**

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Optimum Integral Design – What is new and why is it important?

Figure 5: B0APF coil with field contour

- **Conventional End Designs:**
	- **Conventional ends take large space (~2X coil ID in dipole)** • **Field per unit length in ends is ~1/2 of that in the body => relative loss in field integral is significant in short magnets**

Optimum Integral Design:

- **End turns at midplane runs full length of the coil => almost no loss in space due to Ends**
- **Gain in magnetic length => about a coil diameter in dipole.**
- **This could be a significant fraction of total length in short magnets.**

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Basic Principle of the Optimum Integral Design

Modulation of the current in the straight section (SS) of the conventional designs:

 $I(\theta) = I_o$. cos(n θ)

...and then ends are optimized separately.

Contribution to field from the ends is small and field integral is primarily determined by the length of the SS.

In the optimum integral design, turns at midplane extend full length, while the length of other turns decreases with the angle.

Cos theta azimuthal distribution is obtained in an integral sense, i.e., not in " $I(\theta)$ ", but in " $I(\theta)$. $L(\theta)$ ":

$$
I(\theta) \cdot L(\theta) = I_o \cdot L_i(\theta) \propto I_o \cdot L_o \cdot \cos(n\theta)
$$

Missing current from pole & one region

Computation and Optimization of Integral Field and Field harmonics

$$
b_n = 10^4 \left(\frac{R_0}{a}\right)^n \cos \left[\left(n+1\right) \phi\right] \atop \text{reference radius } R_0
$$

For the optimum integral design, above formula is multiplied by the length of each turn to compute the integral field harmonics (B_n) . Integral Harmonics
 1 B1 B3 B5 B7 B9
 1 37.29 0.94 -0.14 0.01 -0.02
 turn Turns at midplane contribute much more to field

than turns at any other angle. In the "Optimum

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B1 B3 B5 B7 B9

Angle (degree)

37.29 0.94 -0.14 0.01 -0.02

Turns at midplane contribute much more to field

Integral Design" midplane turns extend full-length

First Optimum Integral Magnet: AGS Corrector Dipoles (2004)

- ➢ **Note: Almost the full use of available azimuthal and axial space by the conductor (very high fill factor).**
- ➢ **Some space is needed for the leads at the pole.**
- ➢ **That, and a small azimuthal spacer was sufficient to modulate a natural variation in length for I^o .L.cos() to obtain field quality needed in corrector magnets**

COMPUTED INTEGRAL FIELD HARMONICS IN THE AGS CORRECTOR DIPOLE DESIGN AT A REFERENCE RADIUS OF 60 MM. THE COIL RADIUS IS 90.8 MM. NOTE b_2 IS SEXTUPOLE MUTLIPLIED BY 10^4 (US CONVENTIONS).

Only Direct Wind magnet installed in an accelerator at BNL (in AGS tunnel)

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Optimum Integral Design Opens a New Parameter Space (a parameter space not considered practical for s.c. magnets before)

Model of a short length, high field quality dipole based on the Optimum Integral Design.

Coil length 175 mm; coil diameter 200 mm.

VF VECTOR FIE

(a design example with no spacers in the end)

COMPUTED INTEGRAL FIELD HARMONICS FOR A SHORT DIPOLE (COIL LENGTH < DIAMETER) AT A RADIUS OF 66.6 MM. THE COIL RADIUS IS 100 mm. Note b_2 is sextupole mutliplied by $10^4\,$ (US conventions).

- ➢ **High field quality dipoles with coil length less than the coil diameter**
	- ➢ **Quadrupole magnets with coil length less than the coil radius**
- ➢ **Sextupole magnets with coil length less than 2/3 of the coil radius**

Can the benefits of the optimum integral design be used in EIC?

Length of the Straight Sections (SS) in Various Designs (length of SS determines the integral field in short magnets)

- *Space for turns in the Ends must be at least as much as that used in the arc of the straight section (usually more).*
- *Thus, straight section will have ~1/3 of the length in a cos theta dipole or in a serpentine. It's worse in double-helix.*
- *In the optimum integral design, straight section length is the full coil length.*

Magnet Division PBL A Proposed Value Engineering Design for B1ApF - Ramesh Gupta January 7, 2025 **Optimum Integral**

Motivation for SBIR/STTR – EIC IR has several short magnets B0ApF is the smallest magnet. This may fit in the budget of an STTR Conventional cosine () design, as presented in pCDR: (x-section and ends were optimized separately)

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Comparison of the other designs (double-helix) with the optimum integral was also made for the magnet B0ApF

Optimum integral design extends the magnetic length for the same coil length

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Can the benefits of the optimum integral design be used in EIC? A good topic for SBIR/STTR Program

PBL/BNL STTR on B0ApF (Phase I: 200k\$; Phase II: 1.15M\$)

Goals: Phase I > a Proof-of-Principle dipole; Phase II > a Full-length R&D Magnet

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PBL SBIR/STTR Awards with BNL (EIC awards highlighted)

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Phase I Optimum Integral Dipole

- Phase I original proposal had a scaled down version: Surface contours: 1 short 150 mm long instead of the full-length 600 mm. 2.000000E+00
- However, detailed studies found that it wouldn't be a good technical representation of a full-length design.
- Moreover, 2 layers of 600 mm long Phase I coils can become part of the 10 layers of the Phase II.

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 $000000F + 00$

5.000000E-001

2.317662E-002

As built (two layers of full-length coil, designed, built & tested in the iron yoke)

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Optimum Integral Dipole PBL/BNL STTR for EIC B0ApF (Phase I construction and testing)

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Question #1 for Phase 1:

Will optimum integral design extend the magnetic length as promised?

A good agreement between calculations and measurements

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Question #2 for Phase 1: Will the direct wind coil based on the optimum integral have a good quench performance at this level?

✓ **Answer: Yes... Predicted quench current reached without training !**

Two significant achievements for a Phase I award. A PoP SC magnet in <1 year.

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Magnet Division PBL A Proposed Value Engineering Design for B1ApF -Ramesh Gupta January 7, 2025 **Question for Phase II : Will this excellent performance of the "Direct Wind" technology continue to higher fields and larger bore magnets, e.g., as needed for EIC and other applications?**

Status and Plans of Phase II

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Overall Plan and Goals of Phase II

Final Goal (an ambitious goal for SBIR/STTR program):

10 layers, ~3.8 T bore field, ~4.2 T peak field, 114 mm coil i.d.

For comparison, RHIC dipole: 3.45 T bore field, 80 mm coil i.d.

Intermediate Goal for the Year 1:

- **1. Demonstration of a good field quality:**
- ➢ **Validation of the optimum design and of the 3-D design software**
- **2. Construction and test of the direct wind coil with more layers**
- ➢ **Goal: 6 layers, ~2.9 T bore field, ~3.5 T peak field, 114 mm coil i.d.**

Coil Winding, Magnet Design and Construction for Phase II (Year 1) (a 6-layer optimum integral dipole designed, built and tested)

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A Key Task: Develop *IntegralOpt* **and Associated software (to optimize coil designs, and to create files for coil winding and other software)**

Optimum Integral Dipole for AGS was designed and built in 2004. Those direct-wind coils were optimized with a custom code and then wound with the "legacy software".

A key task of the PBL/BNL STTR:

- ❑ Task #1: The code *IntegralOpt* developed and ported in Phase I will go through a significant upgrade in Phase II and a user manual will be written…
- ✓ **This task is complete now. Twelve layers have been wound with the recent software on two different direct wind machines. No legacy software was used.**
- The optimized design and the computed harmonics have been validated with **the magnetic measurements.**

More on the *IntegralOpt* **Code and Associated Software**

- Optimum Integral code has been fully ported to work on the computers available currently. It is entirely based on the open-source, public domain software.
- \triangleright The program optimizes 3-d coil design with a method different from ROXIE, etc. This alternate method is very fast as it optimizes both 2-d and 3-d coil designs together in a matter of minutes (not days) and that too with up to 200 variables.
- \triangleright The software also creates a set of files for other codes, such as EM software OPERA3d, and input to modern direct wind machine software, etc.
- ❖ Moreover, thanks to the internal ATRO funds, it was updated a few months ago (with only a modest investment in time), so that it can be used for the serpentine pattern as well (a switch was there since 2004, but only implemented recently).

Field Quality Demonstration of the Design and of the Code

13 -0.07 -0.04 *Leads may be contributing to lower order harmonics

14 0.00 0.00 15 0.00 0.00 ➢ **Good field quality despite several changes on the fly (as in most R&D projects)**

16 0.00 0.00 ➢ **Next layers can compensate these small non-zero harmonics**

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A Design Change (not part of the original proposal)

An attempt to remove extra radial space taken by the leads in the design.

SBIR/STTR programs offer unique opportunities to innovate

- ➢ However, one must be prepared that not all ideas will work
- ➢ Here is a case where one innovation for added improvements did not work 100%.
- \triangleright The optimum integral design, and this STTR, as such, didn't depend on this.
- ➢ Another change in the design has eliminated the above issue.

The STTR is back on track now to demonstrate feasibility of the optimum integral dipole for EIC – design, build and test a full-length prototype of EIC dipole B0ApF.

(more information in the backup slides)

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Testing of the Intermediate 6-layer Optimum Integral Dipole

- **Magnet reached only ~70% of the short sample in 5 quenches.**
- **All quenches were in the layers where the new splice was used.**
- **Limited and/or insufficient cooling didn't help- 1 st energization was in <2 hours and subsequent ones with ~20 minutes or less wait.**
- **Limited budget of STTR allowed only ½ day of cryo-testing.**
- **Possibly a higher field could have been reached with more training.**

Optimum Integral Dipole for B1ApF

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Possibility of an Optimum Integral Design for B1ApF

The present design of B1ApF is based on the cable magnet. It has a small Straight Section (SS). Moreover, End Plates (EP) take a significant space of the available slot-length.

Total Length=1.91 m

In a direct-wind optimum integral dipole, the end plates will not be needed and the midplane turns (which create the maximum field) can extend to almost the full slot-length

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Preliminary 2D Magnetic Design B1ApF Cable Magnet Design (last review)

Coil magnetic parameters

The high peak field at block #4 is due to a high number of conductors in this block. An earlier version of the design with 6 blocks had a peak field of 5.3 T. Four-block design was preferred for simpler mechanical assembly. Moreover, the four-block design still has a 30 % margin on the load-line.

Electron-Ion Collider

B1APF proposed 3D coil design

• Large aperture and short slot length causes short straight section length.

Electron-Ion Collider

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Charge #2-5

EIC B1pF/B1ApF Colard Magnets PDR - November 20th & 21st, 2024

Dipole field at coil axis

 31 Charge #2-5

- Short straight section
- Maximum dipole field at center is 3.915 T.
- Integrated dipole field is 4.08 Tm (>4.05 Tm requirement)

Basic Assumptions in Evaluating designs (1)

Rutherford Cable Magnet:

• **Use the design as presented in the last review**

Direct Wind Optimum Integral Dipole:

Minimum turn-to-turn spacing:

- **Type 1: 1.7 mm**
- **Type 2: 1,1 mm (as used in STTR) Larger spacing in the ends.**

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Cables (7 wires) Used in the Calculations (all except one with Type I)

Self-imposed Guidelines in Developing Initial designs

- Inner radius of the additional tube in the Direct Wind B1ApF coil is made the same as the inner radius of the coil in the cable magnet (185 mm)
	- Note magnet before B1ApF is B1pF with coil inner radius of 150 mm
- Center of the cable in the first layer of the Direct Wind coil is placed at a radius of 200 mm to allow sufficient tube thickness (perhaps a smaller value will be sufficient)

- Design must meet the field quality (harmonics) and the integral field requirements.
- Note: All designs are the results of quick optimization for a evaluating the approach. They can be optimized more, but as such, are good enough for initial evaluation.

Initial Investigation of the Optimum Integral Dipole B1ApF (4 layers or 2 double-layer design with Type I Wire)

4-layer design Optimized with the Optimum Integral Code

2001-1 0:\opera\work1\xend\B1ApF\B1ApF-4lyr-200mm-1 9-a1a,X11 - Notepad++

File Edit Search View Encoding Language Settings Tools Macro Run Plugins Window ? 8 8 8 8 6 8 6 4 6 6 7 6 6 7 6 7 6 7 8 7 8 7 7 8 7 8 9 8 8 8 8 8 9 8

B1ApF-4lvr-200mm-1 9-a1a.X11 ☆ 図

Computed harmonics @55 mm (good field quality in coil geometry) low harmonic contents:

Toal number of turns: 509

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Comparison of Field Along the Axis for the Required Field Integral

Cable magnet design

Dipole field at coil axis

Optimum integral design

A wider flap-top and a lower maximum field

 $Z(m)$

Design integral of 4.05 T.m @910 A Maximum field at the center: 2.5 T

Stored Energy at design: 0.55 MJ Inductance: 1.3 Henry

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Computed Performance of 4-layer Direct Wind Optimum Integral Dipole

Computed Performance of 4-layer Direct Wind Optimum Integral Dipole

Since the margin is so large @1.92K, one can consider reducing the length, and operate at a higher current for the same field integral

Design Current 910 A for 4.05 T.m Load line Margin 49%@1.92K

Because of the healthy margin @4.5K, one can validate the design or operate @4.5K

Electron-Ion Collider

31%@4.5K

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Computed Parameters of Optimum Integral B1ApF Dipole (4 layers)

➢ Required integral gradient: 4.05 T.meter

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Direct Wind Optimum Integral Dipole Option for B1ApF (a healthy margin even at 4.5 K with just four layers of Type I)

Sanity Check – Is It Too Good to be True?

As such the optimum integral design has been verified for B0ApF during the PBL/BNL STTR. However, let's do a sanity check of this design for B1ApF.

Compare the Amp-turns required for 1 Tesla central field

- a) cable magnet coil: 301,422 Amp.turns
- b) optimum integral coil: 331,813 Amp.turns
- \checkmark It is reassuring that the two are within 10% of each-other
	- \triangleright A 10% difference is understandable since the two design are optimized with different criterion.

Intermediate Wrap-up of the Direct Wind Optimum Integral Option

- **A 4-layer direct wind optimum integral design for B1ApF will be much cheaper, and faster to design, built and test than the current B1ApF based on the Rutherford cable.**
- **Given that in the PBL/BNL STTR Phase I, a 2-layer direct-wind, optimum integral dipole was designed, built and tested in essentially six months, test results of a 4-layer B1ApF optimum integral dipole should be available in ~1 year and in ~1M\$ (?).**
- The central field in this design is significantly less than that in the cable magnet (~2.5 T **as compared to ~4 T). This means lower Lorentz forces which implies that it's a technically less demanding design. Moreover, 2.5 T field seems to be in a comfortable zone for the direct wind technology, specially given a huge large margin in the design.**
- **A proof-of-principle dipole can be tested in the vertical dewar to full design field at 4 K with a yoke inner radius of ~220 mm and the outer radius to fit the Dewar.**
- **My recommendation will be that we further examine this option without any delay and start working to demonstrate, after appropriate necessary reviews.**
- **This is a prime example of "***value engineering***" that EIC should be proud to advertise!**

Motivation for looking at the other options:

This 4-layer design has too much margin (49% on load line,

92% over the operating), a better optimization is in order.

> Alternate #1: A 2-layer design (instead of 4) with Type I wire > Alternate #2: A 4-layer design with smaller wire (Type II)

Not examined: A 3-layer design with Type I wire

Alternate Option 1

A 2-layer design (only one double layer)

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Initial Investigation of the Optimum Integral Dipole B1ApF (Direct wind, 2 layers or 1 double-layer, 1.92 K Operation)

2-layer design Optimized with the Optimum Integral Code

Number of turns: 258

Comparison of the Field Along the Axis for the Required Field Integral

Cable magnet design Dipole field at coil axis

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Two-layer Optimum integral design

A wider flap-top and a lower maximum field

Design integral of 4.05 T.m @1870 A

Maximum field at the center: 2.5 T

Stored Energy at design: 0.56 MJ Inductance: 0.32 Henry

Computed Quench Performance at 1.92 K of 2-layer Design

Design Current 1870 A for 4.06 T.m

Load line Margin 13%@1.92K

16% margin over the design field

The design could perhaps be optimized more to gain 5% or so. And that may be ok, if past good performance of direct wind technology is repeated. But this may be cutting a bit too close.

Computed Parameters of Optimum Integral B1ApF Dipole (2-layer design operating@1.92K)

➢ Required integral gradient: 4.05 T.meter

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A More Positive Look at the Optimum Integral Direct Wind Option (just two layers of Type I wire sufficient for 1.92 K operation)

Design Current 1870 A for 4.06 T.m

Load line Margin 13%@1.92K

16% margin over the design field

This may be a bit too tight!

Alternate Option 2

A 4-layer design, but with (smaller) Type II wire

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Initial Investigation of the Optimum Integral Dipole B1ApF (Direct wind, 4 layers or 2 double-layer, Type II Wire Option)

Type II wire is smaller

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4-layer Type II Wire Design Optimized with the Optimum Integral Code

Computed harmonics @55 mm (good field quality in coil geometry) low harmonic contents:

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Comparison of the Field Along the Axis for the Required Field Integral

Dipole field at coil axis

Cable magnet design and the Cable magnet design and Desi

Four layers with smaller wire at 625 A A wider flap-top and a lower maximum field

Computed Performance of a Direct-Wind Optimum Integral Dipole Design with four layers Type II Wire

 5.6

 5.1

820

840

 \rightarrow Bpk(T) -Bo(T) \rightarrow 1.92

50

Computed Parameters of Optimum Integral B1ApF Dipole (4-layer Type II design @1.92K and @ 4.5K)

➢ Required integral gradient: 4.05 T.meter

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Yet another Option for the Optimum Integral Direct Wind (a reasonable margin even at 4.5 K with four layers of Type II)

Design Current 625 A for 4.06 T.m

Load line Margin

41%@1.92K

20%@4.5K

A More Enterprising Option

> Looking beyond just B1ApF

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A More Enterprising Option to Consider

In addition to possibly making B1ApF a direct wind magnet, imagine B1pF as two B1ApF. Then three identical B1ApF will generate the same total integral field (4.05+10.34 ~14.4 T.m); each 14.4/3=4.8 T.m

- Note: I am not suggesting to slow down the B1pF cable magnet program. I suggest consider a direct wind B1ApF option with above parameter (1.75 m long, 4.8 T.m).
- ❑ Coils will be identical, even if some have larger aperture than the minimum required. ❑ This will reduce the variety of magnet coils and reduce the number of spares, etc. ❑ Yoke will be different, but yokes can be stored separately and assembled as needed.
	- **Compare various interfaces between B1pF & B1ApF Vs 3 B1ApF coils.**

Optimum Integral Dipole B1ApF Optimized so that two of these could replace one of B1pF (4 layers, Type I Wire)

➢ Required field integral for B1ApF only option is 4.05 T.m. \triangleright It increases to 4.8 T, m for three B1ApF replacing B1pF & B1ApF.

Comparison of the Field Along the Axis for the Required Field Integral (two B1Apf >> One B1pF option) Cable magnet design Optimum integral design Four layers higher field integral option

Dipole field at coil axis

National Laboratory

$Z(m)$

Design integral of 4.05 T/m @1000 A for B1ApF option only. Integral of 4.8 T.m @1200 A for 2 B1ApF making 1 B1pF. Maximum field at the center: 2.8 T and 3.2 T

> Inductance: 1.2 Henry Stored Energy at design: 0.86 MJ @1200 A

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Yet another Option for the Optimum Integral Direct Wind (a reasonable margin even at 4.5 K with four layers of Type II)

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Computed Performance of a Direct-Wind Optimum Integral 4-Layer Design Optimize for B1pF and B1ApF

6

5.8

5.6

5.4

 5.2

 $B(T)$

 \rightarrow Bpk(T)

 $+1.92$

1760

 $-BO(T)$

1780

1800

1820

4-layer Type II Wire Design Optimized with the Optimum Integral Code (two B1Apf >> One B1pF option)

Computed harmonics @55 mm (good field quality in coil geometry) low harmonic contents:

**Magnet Division Computer Computer Super States of turns: 509

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Computed Parameters of Optimum Integral B1ApF Dipole (4-layer Type II design @1.92K and @ 4.5K)

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➢ Required integral gradient: 4.05 T.meter

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Selected Direct Wind Optimum Integral Dipole Options for B1ApF

Required field integral for B1ApF : 4.05 T.meter

Required field integral for the three B1ApF replacing B1pF and B1ApF: 4.8 T.meter

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Summary

- **Work under the STTR has shown that an optimum integral direct wind dipole is an alternative to the current design of B1ApF based on the Rutherford cable.**
- **A 4-layer direct wind optimum integral B1ApF will be much cheaper and faster to build and test than the cable magnet. A proof-of-principle B1ApF based on this design should be available in ~1 year and in ~1M\$ (?), with reusable coils.**
- **The central field in this design is significantly smaller than that in the cable magnet. This means lower Lorentz and a technically less demanding design. All 4-layer designs have comfortable margin, and they can be tested at ~4K.**
- **Furthermore, the length of B1ApF can be properly chosen so that two of these could replace one of B1pF.**
- **This provides an alternate design option for the B1pF dipole for no added cost.**
- **This is a prime example of value engineering. Given the large potential gains, we should examine this further now and build a PoP after appropriate reviews.**

Extra Slides

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A Proposed Value Engineering Design for B1ApF -Ramesh Gupta January 7, 2025
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Cable Used in the Calculations (7 wires)

Performance computed at 1.92 K and 4.5 K Wire Dia (mm) Cu:NC Min Ic $Jc(7T, 4.2K)$
A/mm² Scaled Jc
(5T,4.2K) A/mm² $(TT, 4.2K)$ A 6 Rutherford cable 1.065 550 1605 2729 1.60 Direct wind type 1* 0.47 1.60 105 1574 2675 5 1733 Direct wind type 2* 0.33 1.60 57 2946 $\mathsf{B}(\mathsf{T})$ $\overline{4}$ **TYPE I** -1.92 3 $-0 - 4.5$ 8 $\overline{2}$ $\overline{7}$ 6 800 1000 1200 1400 1600 1800 2000 2200 24 $lc(A)$ 5 There may be $B(T)$ a slight 4 degradation in -1.92 3 going from $-0 - 4.5$ wire to cable. $\overline{2}$ However, past $\mathbf 1$ experience is that Ic of wires $\mathbf 0$ as delivered, 500 1000 1500 2000 2500 3000 $\bf{0}$ more than $lc(A)$ offsets that. **Magnet Division Magnet Division A** Proposed Value Engineering Design for B1ApF -Ramesh Gupta January 7, 2025 **Brookhaven**

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Cable Used in the Calculations (7 wires)

Charge 2 **Requirements and Preliminary Magnetic Design**

Design Requirements

Optimized coil specs

Electron-Ion Collider

EIC B1pF/B1ApF Collared Magnets PDR - November 20th & 21st, 2024

Magnet Division PBL A Proposed Value Engineering Design for B1ApF -Ramesh Gupta January 7, 2025⁷²
B1pF (and computation of length 3 B1ApF making B1pF+B1ApF)

A Proposed Value Engineering Design for B1ApF - Ramesh Gupta January 7, 2025 **Center to center distance between B1pF & B1ApF zd = 21.313-18.565 = 2.748 m End Plate to End Plate in B1pF, B1ApF" 3.4 m, 1.91 m End plate to End Plate between B1pF & B1ApF: 2.748+3.4/2+1.91/2=5.4 m (space for direct wind coil) Length of B1ApF: 5.4/3=1.8 m;1.75 m leaves 100 mm gap**

Magnet Division Contains A Proposed Value Engineering Design for B1ApF -Ramesh Gupta January 7, 2025 ⁷⁴

More slides on PBL/BNL STTR Phase II

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A Change in Design to Eliminate Radial Space Used by Leads

- **Phase I design used extra radial space for bringing leads out "over the coil" at the pole.**
- **Can this use of extra radial space be saved to make design more efficient?**

Phase I configuration

Magnet Division Configuration

Magnet Division Paul A Proposed Value Engineering Design for B1ApF -Ramesh Gupta January 7, 2025

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A Change in Design to Eliminate Radial Space Used by Leads

- ❑ **A new idea was found to eliminate the above-mentioned extra radial space.**
- ❑ **Bring leads out at the midplane (as in the picture) – avoid extra radial space.**
- ❑ **Everyone then thought that it was a brilliant idea, at that time.**
- ❑ **However, this meant adding a splice at pole – a high field region.**
- ❑ **Such a splice had never been made before in any direct wind magnet with the 6-around-1 cable. Need to test this before implementing in the whole magnet.**

Internal Splice is here

Phase II configuration

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Recovery Plan for Remaining Phase II:

- **Implement the lessons learned (go back to original splice).**
- **Operate compromised (innovative) coils at a safe (lower) current.**
- **Add extra layers to get the original amp-turns.**
- ➢ **Coordinate this program with LDRD on quench propagation study to overcome the budgetary challenges.**
- ✓ **This is essentially allowing us to test the original targets/goals.**

Updated Plan for the Phase II Dipole

▪ **The original plan was for 5 double-layer (10 single-layer), all connected in series.**

I (1&2) I (3&4) I (5&6) I (7&8) I (9&10)

- **The revised plan is for 6 double-layer (12 single-layer). Double layers 3&4 and 5&6 will be in parallel to each other. They will be in series to the rest of the four double layer. This will make it effectively (to first order) a 5-layer coil again and will test the original design goals/principles.**
- **Double layers 3&4 + 5&6 can be safely used as both have reached >50% of the design current.**
- ➢ **Original plan: five double layers for certain Amp-turns**

I/2 (3&4)

m V_{L}

 $\delta \alpha$

m

 $V_{\rm R}$

I/2 (5&6)

I (1&2)

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I (7&8) I (9&10) I (11&12)

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Two extra

layers wound